

A New Probability Distribution for Modeling Failure and Service Times: Properties, Copulas and Various Estimation Methods

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Abstract In this paper, a new generalization of the Pareto type II model is introduced and studied. The new density can be “right skewed” with heavy tail shape and its corresponding failure rate can be “J-shape”, “decreasing” and “upside down (or increasing-constant-decreasing)”. The new model may be used as an “under-dispersed” and “over-dispersed” model. Bayesian and non-Bayesian estimation methods are considered. We assessed the performance of all methods via simulation study. Bayesian and non-Bayesian estimation methods are compared in modeling real data via two applications. In modeling real data, the maximum likelihood method is the best estimation method. So, we used it in comparing competitive models. Before using the the maximum likelihood method, we performed simulation experiments to assess the finite sample behavior of it using the biases and mean squared errors.

Keywords Pareto type II Distribution, Estimation, Simulations, Copulas, Renyi Copula, Farlie Gumbel Morgenstern Family, Ordinary Least Square, Bayesian Estimation.

AMS 2010 subject classifications 62E10, 62N01, 62N02

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1. Introduction

The Pareto type II (also called as Lomax) distribution is a heavy-tail probability distribution used in business, actuarial science, biological sciences, engineering, economics, income and wealth inequality, queueing theory, size of cities, and Internet traffic modeling (see Lomax [41]). It has been applied to model data obtained from income and wealth (Harris [34] and Atkinson and Harrison [10]), firm size (Corbellini et al. [31]) and reliability and life testing (Hassan and Al-Ghamdi [35]). The Pareto type II model is known as a special model form of Pearson type VI distribution and has also considered as a mixture of exponential (Exp) and gamma (Gam) distributions. The Pareto type II model belongs to the family of “decreasing” hazard rate function (HRF) and considered as a limiting model of residual lifetimes at great age (Balkema and de Hann [19] and Chahkandi and Ganjali [21]). The Pareto type II distribution has been suggested as heavy tailed alternative to the Exp, Weibull (W) and Gam distributions (Bryson [20]). For details about relation between the Pareto type II model and the Burr family and Compound Gamma (CGam) model see Tadikamalla [62] and Durbey [24].

The main aim of this work is to provide a flexible extension of the Pareto type II distribution using the odd Burr-G (OB-G) family defined by Alizadeh et al. [6]. Bayesian and Non-Bayesian estimation methods such as uch as the maximum likelihood estimation (MLE), ordinary least square estimation (OLSE), weighted least square estimation

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(WLSE) and the Kolmogorov estimation (KE) are considered. The Bayesian estimation method under the squared error loss function (SELF). The new model proved its ability in modeling

- The monotonically increasing hazard rate data.
- The bimodal left skewed real data sets.
- The bimodal right skewed real data sets.

A random variable (rv) Z has the Pareto type II (P) distribution with two parameters α and β if it has cumulative distribution function (CDF) (for $Z > 0$) given by

$$G_{\alpha,\beta}(z) = 1 - \left(1 + \frac{z}{\beta}\right)^{-\alpha}, \quad (1)$$

where $\alpha > 0$ and $\beta > 0$ are the shape and scale parameters, respectively. Then the corresponding probability density function (PDF) of (1) is

$$g_{\alpha,\beta}(z) = \frac{\alpha}{\beta} \left(1 + \frac{z}{\beta}\right)^{-(\alpha+1)}. \quad (2)$$

Due to Alizadeh et al. [6], the CDF of the OB-G family is given by

$$F_{v,\theta,\zeta}(z) = 1 - \frac{\overline{G}_{\zeta}(z)^{v\theta}}{\left[G_{\zeta}(z)^v + \overline{G}_{\zeta}(z)^v\right]^{\theta}}, \quad (3)$$

where $\overline{G}_{\zeta}(z) = 1 - G_{\zeta}(z)$. The PDF corresponding to (3) is given by

$$f_{v,\theta,\zeta}(z) = \frac{v\theta g_{\zeta}(z) G_{\zeta}(z)^{v-1} \overline{G}_{\zeta}(z)^{v\theta-1}}{\left[G_{\zeta}(z)^v + \overline{G}_{\zeta}(z)^v\right]^{1+\theta}}. \quad (4)$$

For $\theta = 1$, the OB-G family reduces to the Odd G (O-G) family (see Gleaton and Lynch [42]). For $v = 1$, the OB-G family reduces to the proportional reversed hazard rate (PRHR) family. The odd Burr Pareto type II (OBP) survival function (SF) is given by

$$S_{\xi}(z) |_{(\xi=v,\theta,\alpha,\beta)} = \frac{\nabla_{\beta}(z)^{-\alpha v\theta}}{\left\{[1 - \nabla_{\beta}(z)^{-\alpha}]^v + \nabla_{\beta}(z)^{-\alpha v}\right\}^{\theta}}, \quad (5)$$

where $\nabla_{\beta}(z) = 1 + \frac{z}{\beta}$ and $S_{\xi}(z) = 1 - F_{\xi}(z) |_{(\xi=v,\theta,\alpha,\beta)}$. For $\theta = 1$, the OBP reduces to the odd Pareto type II. For $v = 1$, the OBP reduces to the proportional reversed hazard rate Pareto type II. The PDF corresponding to (5) is given by

$$f_{\xi}(z) = v\theta \frac{\alpha}{\beta} \frac{\nabla_{\beta}(z)^{-(\alpha v\theta+1)} [1 - \nabla_{\beta}(z)^{-\alpha}]^{v-1}}{\left\{[1 - \nabla_{\beta}(z)^{-\alpha}]^v + \nabla_{\beta}(z)^{-\alpha v\theta}\right\}^{1+\theta}}. \quad (6)$$

The HRF for the new model can be derived from $f_{\xi}(z) / S_{\xi}(z)$. Many useful Pareto type II extensions can be found in Tahir et al. [64] (Weibull Pareto type II distribution), Cordeiro et al. [23] (the one parameter Pareto type II system of densities), Altun et al. [12] (Odd log-logistic Pareto type II), Altun et al. [12] (Zografos-Balakrishnan Pareto type II distribution), Elbiely and Yousof [33] (Weibull generalized Pareto type II, Rayleigh generalized Pareto type II and Exponential generalized Pareto type II distributions), Yousof et al. [66] (Topp Leone Poisson Pareto type II distribution), Goual and Yousof [43] (Pareto type II inverse Rayleigh), Gad et al. [27] (Burr type XII Pareto type II, Pareto type II Burr type XII and Pareto type II Pareto type II distributions), Yadav et al. [65] (Topp Leone Pareto type II distribution) and Ibrahim and Yousof [36] (Poisson Burr X generalized

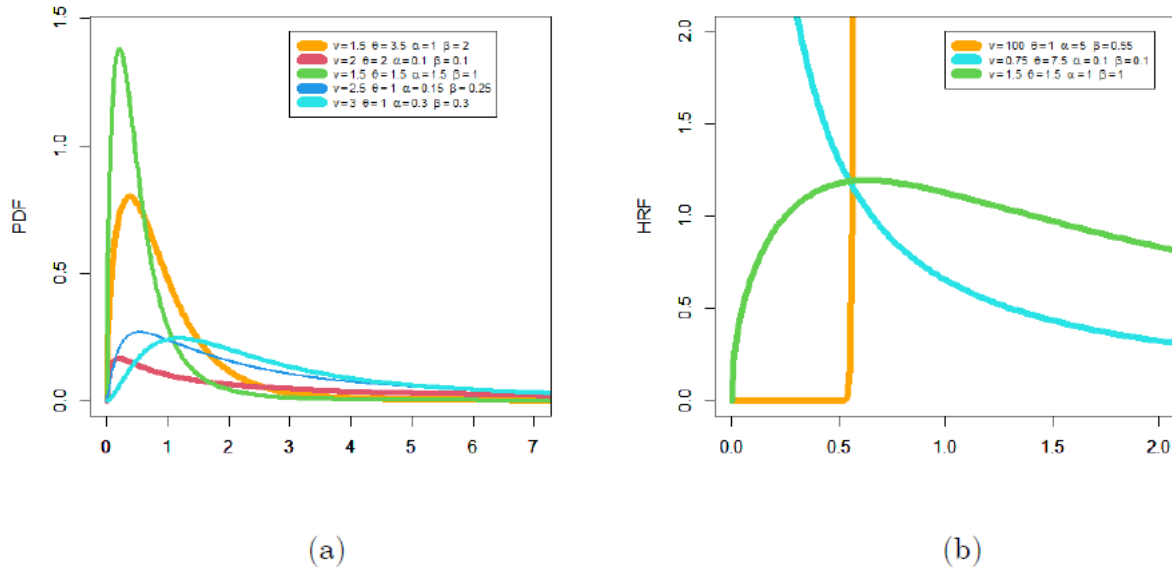


Figure 1. PDF and HRF plots for some selected parameters value.

Pareto type II and Poisson Rayleigh generalized Pareto type II distributions). To illustrate the flexibility of the new PDF and its corresponding HRF we present Figure 1. Figure 1(a) gives some PDF plots for some selected parameters value. Figure 1(b) gives some HRF plots for some selected parameters value. Based on Figure 1(a) the OBP density can be right skewed with heavy tail shape. Based on Figure 1(b) the OBP HRF can be “J-shape” ($v = 100, \theta = 1, \alpha = 5, \beta = 0.55$), “decreasing” ($v = 0.75, \theta = 7.5, \alpha = 0.1, \beta = 0.1$) and “upside down (or increasing-constant-decreasing)” ($v = 1.5, \theta = 1.5, \alpha = \beta = 1$).

2. Extensions via copula

In this section, we derive some new bivariate type OBP (BOBP) models using Farlie Gumbel Morgenstern (FGM) copula (see Kotz and Johnson [50], Kotz and Johnson [51], Gumbel [44] and Gumbel [45]), modified FGM copula (see Rodriguez-Lallena and Ubeda-Flores [60]) and Clayton copula and Renyi entropy copula (Pougaza and Djafari [59]). The multivariate OBP (MOBP) type is also presented. However, future works may be allocated to study these new models. First, we consider the joint CDF of the FGM family, where $\mathbf{H}_\rho(\tau, \varsigma) = \tau\varsigma(1 + \rho\bar{\tau}\bar{\varsigma}) |_{\bar{\tau}=1-\tau, \bar{\varsigma}=1-\varsigma}$ with the marginal functions $\tau = F_{\xi_1}(z_1), \varsigma = F_{\xi_2}(z_2), \rho \in (-1, 1)$ is a dependence parameter and for every $\tau, \varsigma \in (0, 1), \mathbf{H}(\tau, 0) = \mathbf{H}(0, \varsigma) = 0$ which is “grounded minimum” and $\mathbf{H}(\tau, 1) = \tau$ and $\mathbf{H}(1, \varsigma) = \varsigma$ which is “grounded maximum”, $\mathbf{H}(\tau_1, \varsigma_1) + \mathbf{H}(\tau_2, \varsigma_2) - \mathbf{H}(\tau_1, \varsigma_2) - \mathbf{H}(\tau_2, \varsigma_1) \geq 0$. For more details see Elgohari and Yousof [25], Elgohari and Yousof [26], Al-babtain et al. [3], Ali et al. [4] and Ali et al. [5].

2.1. BOBP type via FGM copula

A copula is continuous in τ and ς ; actually, it satisfies the stronger Lipschitz condition, where

$$|\mathbf{H}(\tau_2, \varsigma_2) - \mathbf{H}(\tau_1, \varsigma_1)| \leq |\tau_2 - \tau_1| + |\varsigma_2 - \varsigma_1|.$$

For $0 \leq \tau_1 \leq \tau_2 \leq 1$ and $0 \leq \varsigma_1 \leq \varsigma_2 \leq 1$, we have

$$\Pr(\tau_1 \leq \tau \leq \tau_2, \varsigma_1 \leq \varsigma \leq \varsigma_2) = \mathbf{H}(\tau_1, \varsigma_1) + \mathbf{H}(\tau_2, \varsigma_2) - \mathbf{H}(\tau_1, \varsigma_2) - \mathbf{H}(\tau_2, \varsigma_1) \geq 0.$$

Then, setting $\bar{\tau} = 1 - F_{\xi_1}(z_1)|_{[\bar{\tau}=(1-\tau)\in(0,1)]}$ and $\bar{\varsigma} = 1 - F_{\xi_2}(z_2)|_{[\bar{\varsigma}=(1-\varsigma)\in(0,1)]}$, we can easily obtain the joint CDF of the FGM family. The joint PDF can then be derived from $c_\rho(\tau, \varsigma) = 1 + \rho\tau\bar{\varsigma}|_{(\tau=1-2\tau \text{ and } \varsigma=1-2\varsigma)}$ or from $c(z_1, z_2) = \mathbf{H}\left(F_{\xi_1}(z_1), F_{\xi_2}(z_2)\right) f_{\xi_1}(z_1) f_{\xi_2}(z_2)$.

2.2. BOBP type via modified FGM copula

The modified FGM copula is defined as $\mathbf{H}_\rho(\tau, \varsigma) = \tau\varsigma [1 + \rho\vartheta(\tau) \Phi(\varsigma)]|_{\rho\in(-1,1)}$ or $\mathbf{H}_\rho(\tau, \varsigma) = \tau\varsigma + \rho\tilde{\vartheta}_\tau\tilde{\Phi}_\varsigma|_{\rho\in(-1,1)}$, where $\tilde{\vartheta}_\tau = \tau\vartheta(\tau)$, and $\tilde{\Phi}_\varsigma = \varsigma\Phi(\varsigma)$ and $\vartheta(\tau)$ and $\Phi(\varsigma)$ are two continuous functions on $(0, 1)$ with $\vartheta(0) = \vartheta(1) = \Phi(0) = \Phi(1) = 0$. Let

$$\alpha_1(\tau) = \inf \left\{ \tilde{\vartheta}_\tau : \frac{\partial}{\partial \tau} \tilde{\vartheta}_\tau |_{\sigma_1} \right\} < 0, \alpha_2(\tau) = \sup \left\{ \tilde{\vartheta}_\tau : \frac{\partial}{\partial \tau} \tilde{\vartheta}_\tau |_{\sigma_1(\varsigma)} \right\} < 0,$$

$$\theta_1(\varsigma) = \inf \left\{ \tilde{\Phi}_\varsigma : \frac{\partial}{\partial \varsigma} \tilde{\Phi}_\varsigma |_{\sigma_2} \right\} > 0, \theta_2(\varsigma) = \sup \left\{ \tilde{\Phi}_\varsigma : \frac{\partial}{\partial \varsigma} \tilde{\Phi}_\varsigma |_{\sigma_2(\tau)} \right\} > 0.$$

Then, $1 \leq \min(\alpha_1(\tau) \alpha_2(\tau), \theta_1(\varsigma) \theta_2(\varsigma)) < \infty$, where $\tau \frac{\partial}{\partial \tau} \vartheta(\tau) = \frac{\partial}{\partial \tau} \tilde{\vartheta}_\tau - \vartheta(\tau)$, $\sigma_1(\varsigma) = \left\{ \tau : \tau \in (0, 1) \mid \frac{\partial}{\partial \tau} \tilde{\vartheta}_\tau \text{ exists} \right\}$ and $\sigma_2(\tau) = \left\{ \varsigma : \varsigma \in (0, 1) \mid \frac{\partial}{\partial \varsigma} \tilde{\Phi}_\varsigma \text{ exists} \right\}$.

• Type-I

Consider the following functional form for both $\tilde{\vartheta}_\tau$ and $\tilde{\Phi}_\varsigma$ where $\tilde{\vartheta}_\tau = \tau \left[1 - F_{\xi_1}(\tau) \right]$ and $\tilde{\Phi}_\varsigma = \varsigma \left[1 - F_{\xi_2}(\varsigma) \right]$. Then, the BOBP-FGM (Type-I) can be derived from $\mathbf{H}_\rho(\tau, \varsigma) = \tau\varsigma + \rho\tilde{\vartheta}_\tau\tilde{\Phi}_\varsigma|_{\rho\in(-1,1)}$

• Type-II

Let $\vartheta(\tau)$ and $\Phi(\varsigma)$ be two functional forms satisfy all the conditions stated earlier where $\vartheta(\tau)|_{(\rho_1>0)} = \tau^{\rho_1} (1 - \tau)^{1-\rho_1}$ and $\Phi(\varsigma)|_{(\rho_2>0)} = \varsigma^{\rho_2} (1 - \varsigma)^{1-\rho_2}$. Then, the corresponding BOBP-FGM (Type-II) can be derived from $\mathbf{H}_{\rho, \rho_1, \rho_2}(\tau, \varsigma) = \tau\varsigma [1 + \rho\vartheta(\tau) \Phi(\varsigma)]$.

• Type-III

Let $\widetilde{\vartheta}(\tau) = \tau [\log(1 + \bar{\tau})]|_{\bar{\tau}=1-\tau}$ and $\widetilde{\Phi}(\varsigma) = \varsigma [\log(1 + \bar{\varsigma})]|_{\bar{\varsigma}=1-\varsigma}$. In this case, one can also derive a closed form expression for the associated CDF of the BOBP-FGM (Type-III) from $\mathbf{H}_\rho(\tau, \varsigma) = \tau\varsigma \left(1 + \rho\widetilde{\vartheta}(\tau) \widetilde{\Phi}(\varsigma) \right)$.

• Type-IV

The CDF of the BOBP-FGM (Type-IV) model can be derived from $\mathbf{H}(\tau, \varsigma) = \tau F_{\xi_2}^{-1}(\varsigma) + \varsigma F_{\xi_1}^{-1}(\tau) - F_{\xi_1}^{-1}(\tau) F_{\xi_2}^{-1}(\varsigma)$ where $F_{\xi_1}^{-1}(\tau)$ and $F_{\xi_2}^{-1}(\varsigma)$ can be easily derived from (5).

2.3. BOBP type via Ali–Mikhail–Haq copula

Under the stronger Lipschitz condition, the joint CDF of the archimedean Ali–Mikhail–Haq copula can expressed as

$$\mathbf{H}(\varsigma_1, \varsigma_2) = \frac{\varsigma_1\varsigma_2}{1 - \rho\varsigma_1\varsigma_2} |_{\rho\in(-1,1)},$$

the corresponding joint PDF of the archimedean Ali–Mikhail–Haq copula can expressed as

$$\mathbf{h}(\varsigma_1, \varsigma_2) = \frac{1 - \rho + 2\rho\frac{\varsigma_1\varsigma_2}{1 - \rho\varsigma_1\varsigma_2}}{[1 - \rho\varsigma_1\varsigma_2]^2} |_{\rho\in(-1,1)},$$

sitting $\bar{\varsigma}_1 = 1 - F_{\xi_1}(z_1)$ and $\bar{\varsigma}_2 = 1 - F_{\xi_1}(z_1)$ we can derive the joint CDF and the joint PDF of the BOBP type via Ali–Mikhail–Haq copula.

2.4. BOBP and MOBP type via Clayton copula

The Clayton copula can be considered as $\mathbf{H}(\varsigma_1, \varsigma_2) = [(1/\varsigma_1)^\rho + (1/\varsigma_2)^\rho - 1]^{-\rho^{-1}} |_{\rho \in (0, \infty)}$. Setting $\varsigma_1 = F_{\Phi_1}(t)$ and $\varsigma_2 = F_{\Phi_2}(x)$, the BOBP type can be derived from $\mathbf{H}(\varsigma_1, \varsigma_2) = \mathbf{H}(F_{\xi_1}(t), F_{\Phi_2}(x))$. Similarly, the MOBP (m -dimensional extension) from the above can be derived from $\mathbf{H}(\varsigma_n) = (\sum_{n=1}^m \varsigma_n^{-\rho} + 1 - m)^{-\rho^{-1}}$.

2.5. BOBP type via Renyi's entropy copula

Using the theorem of Pougaza and Djafari [59] where $\mathbf{H}(\tau, \varsigma) = \mathbf{z}_2\tau + \mathbf{z}_1\varsigma - \mathbf{z}_1\mathbf{z}_2$, the associated BOBP will be $\mathbf{H}(u, \varsigma) = \mathbf{H}(F_{\underline{V}_1}(\mathbf{z}_1), F_{\underline{V}_2}(\mathbf{z}_2))$.

3. Mathematical properties

3.1. Asymptotics and quantile function

In mathematical analysis, the asymptotic analysis is used for describing the limiting behavior of some functions. Asymptotics derivations for the CDF, PDF and HRF can be obtained for the new model. The asymptotics of the CDF, PDF and HRF as $z \rightarrow 0$ are given by

$$F_{\xi}(z) \sim \theta[1 - \nabla_{\beta}(z)^{-\alpha}]^v |_{z \rightarrow 0}, f_{\xi}(z) \sim v\theta \frac{\alpha}{\beta} \nabla_{\beta}(z)^{-(\alpha+1)} [1 - \nabla_{\beta}(z)^{-\alpha}]^{v-1} |_{z \rightarrow 0},$$

and

$$h_{\xi}(z) \sim v\theta \frac{\alpha}{\beta} \nabla_{\beta}(z)^{-(\alpha+1)} [1 - \nabla_{\beta}(z)^{-\alpha}]^{v-1} |_{z \rightarrow 0},$$

The asymptotics of CDF, PDF and HRF as $z \rightarrow \infty$ are given by

$$S_{\xi}(z) \sim v^{\theta} \nabla_{\beta}(z)^{-\alpha\theta} |_{z \rightarrow \infty}, f_{\xi}(z) \sim \theta v^{\theta} \frac{\alpha}{\beta} \nabla_{\beta}(z)^{-\alpha v - 1} |_{z \rightarrow \infty}$$

and

$$h_{\xi}(z) \sim \theta \frac{\alpha}{\beta} \nabla_{\beta}(z)^{-1} |_{z \rightarrow \infty},$$

For simulation of this new model, we obtain the quantile function (QF) of Z (by inverting (5)), say $\mathbf{z}_u = F^{-1}(u)$, as

$$\mathbf{z}_u = \beta \left\{ \left[\frac{\left(1 - u^{\frac{1}{\theta}}\right)^{\frac{1}{v}}}{u^{\frac{1}{v\theta}} + \left(1 - u^{\frac{1}{\theta}}\right)^{\frac{1}{v}}} \right]^{-\frac{1}{\alpha}} - 1 \right\}. \tag{7}$$

Equation (7) is used for simulating the new model.

3.2. Useful representations

Due to Alizadeh et al. (2017a), the PDF in (6) can be expressed as

$$f(\mathbf{z}) = \sum_{s=0}^{\infty} \eta_s g_{s^{\bullet}, \alpha, \beta}(\mathbf{z}) |_{s^{\bullet}=1+s}, \tag{8}$$

where

$$\eta_s = \frac{v\theta}{s^{\bullet}} \sum_{j_1, j_2=0}^{\infty} \sum_{j_3=s}^{\infty} (-1)^{j_2+k+s} \binom{-(1+\theta)}{j_1} \binom{-[v(1+j_1)+1]}{j_2} \binom{v(1+j_1)+j_2+1}{j_3} \binom{j_3}{s},$$

and $g_{s^\bullet, \alpha, \beta}(z)$ is the PDF of the F model with power parameter s^\bullet . By integrating Equation (8), the CDF of Z becomes

$$F(z) = \sum_{s=0}^{\infty} \eta_s G_{s^\bullet, \alpha, \beta}(z), \tag{9}$$

where $G_{s^\bullet, \alpha, \beta}(z)$ is the CDF of the Pareto type II distribution with power parameter s^\bullet .

3.3. Moments and incomplete moments

The r^{th} ordinary moment of Z is given by

$$\mu'_{r,Z} = E(z^r) = \int_{-\infty}^{\infty} z^r f(z) dz,$$

then we obtain

$$\mu'_{r,Z} = \sum_{s=0}^{\infty} \sum_{\kappa=0}^r \eta_s s^\bullet \beta^r (-1)^\kappa \binom{r}{\kappa} \mathcal{B}\left(s^\bullet, 1 + \frac{1}{\alpha}(\kappa - r)\right) |_{(\alpha > r)}, \tag{10}$$

where $\mathcal{B}(w_1, w_2) = \int_0^1 m^{w_1-1} (1 - m)^{w_2-1} dm$. Setting $r = 1, 2, 3$ and 4 in (10), we have

$$\begin{aligned} E(Z) &= \sum_{s=0}^{\infty} \sum_{\kappa=0}^1 \eta_s s^\bullet \beta (-1)^\kappa \binom{1}{\kappa} \mathcal{B}\left(s^\bullet, \frac{1}{\alpha}(\kappa - 1) + 1\right) |_{(\alpha > 1)}, \\ E(Z^2) &= \sum_{s=0}^{\infty} \sum_{\kappa=0}^2 \eta_s s^\bullet \beta^2 (-1)^\kappa \binom{2}{\kappa} \mathcal{B}\left(s^\bullet, \frac{1}{\alpha}(\kappa - 2) + 1\right) |_{(\alpha > 2)}, \\ E(Z^3) &= \sum_{s=0}^{\infty} \sum_{\kappa=0}^3 \eta_s s^\bullet \beta^3 (-1)^\kappa \binom{3}{\kappa} \mathcal{B}\left(s^\bullet, \frac{1}{\alpha}(\kappa - 3) + 1\right) |_{(\alpha > 3)}, \end{aligned}$$

and

$$E(Z^4) = \sum_{s=0}^{\infty} \sum_{\kappa=0}^3 \eta_s s^\bullet \beta^4 (-1)^\kappa \binom{4}{\kappa} \mathcal{B}\left(s^\bullet, \frac{1}{\alpha}(\kappa - 4) + 1\right) |_{(\alpha > 4)},$$

where $E(Z) = \mu'_1$ is the mean of Z . The r^{th} incomplete moment, say $\mathcal{I}_r(t)$, of Z can be expressed, from (9), as

$$\mathcal{I}_{r,Z}(t) = \int_{-\infty}^t z^r f(z) dz = \sum_{s=0}^{\infty} \eta_s \int_{-\infty}^t z^r g_{s^\bullet, \alpha, \beta}(z) dz$$

then

$$\mathcal{I}_{r,Z}(t) = \sum_{s=0}^{\infty} \sum_{\kappa=0}^r \eta_s s^\bullet \beta^r (-1)^\kappa \binom{r}{\kappa} \mathcal{B}_t\left(s^\bullet, 1 + \frac{1}{\alpha}(\kappa - r)\right) |_{(\alpha > r)},$$

where $\mathcal{B}_y(w_1, w_2) = \int_0^y m^{w_1-1} (1 - m)^{w_2-1} dm$. The first incomplete moment given by (11) with $r = 1$ as

$$\mathcal{I}_{1,Z}(t) = \sum_{s=0}^{\infty} \sum_{\kappa=0}^1 \eta_s s^\bullet \beta (-1)^\kappa \binom{1}{\kappa} \mathcal{B}_t\left(s^\bullet, \frac{1}{\alpha}(\kappa - 1) + 1\right) |_{(\alpha > 1)}.$$

The index of dispersion I_{xDis} or the variance to mean ratio can derived as $I_{xDis}(z) = \mu_2/\mu'_1$. It is a measure used to quantify whether a set of observed occurrences are clustered or dispersed compared to a standard statistical model.

3.4. Numerical and graphical analysis

By analyzing the mean $[E(Z)]$, variance $[Var(Z)]$, skewness $[Skew(Z)]$, kurtosis $[Kur(Z)]$ and $IxDis(Z)$ numerical in Table 1 we noted that, the $Skew(Z)$ of the OBP distribution can range in the interval $(-69216.87, 98983.16)$. The spread for the $Kur(Z)$ of the OBP model is ranging from 74.17124 to ∞ . The $IxDis(Z)$ for the OBP model can be in $(0, 1)$ and also > 1 so it may be used as an “under-dispersed” and “over-dispersed” model. Figure 2 gives some three dimensional skewness plots for parameter α . The flexibility of the skewness of the new model are proved in Figures 2 and 3 using some some three dimensional plots. The flexibility of the kurtosis of the new model are proved in Figures 4 and 5 using some some three dimensional plots. Figure 3 gives some three dimensional skewness plots for parameter θ . Figure 4 gives some three dimensional kurtosis plots for parameter α . Finally, Figure 5 gives three dimensional kurtosis plots for parameter θ .

Table 1: $E(Z)$, $Var(Z)$, $Skew(Z)$ and $Kur(Z)$ of the OBP model.

v	θ	α	β	$E(Z)$	$Var(Z)$	$Skew(Z)$	$Kur(Z)$	$IxDis(Z)$
1	1.5	10	1.5	0.1071429	0.01324568	2.4825320	13.63030	0.1236264
5				0.1003165	0.0005641241	0.4022094	4.077114	0.0056234
10				0.1033713	0.0001518643	0.0196449	3.829237	0.0014691
50				0.1066996	6.535887e-06	-69216.87*	8673587	6.126 × 10 ⁻⁵
100				7.9602 × 10 ⁻⁰⁵	9.18712 × 10 ⁻⁰⁷	120.4033	14497.96	0.1154139
200				1.1781 × 10 ⁻¹¹	1.35973 × 10 ⁻¹²	98983.16*	∞ *	0.1154218
5	0.5	5	5	0.9647359	0.16261690	2.478782	16.67835	0.168561
	1			0.7659348	0.04623618	1.026232	6.366972	0.060366
	10			0.4800206	0.00957576	-0.3233682	3.074851	0.019949
	50			0.3618845	0.00549617	-0.3826962	3.042526	0.015188
	100			0.3201573	0.00438074	-0.3796808	3.025701	0.013683
	200			0.2828904	0.00348778	-0.3717237	3.008953	0.012329
2.5	2.5	5	10	1.076590	0.22120710	0.729365	4.209933	0.2054701
		50		0.101967	0.00179817	0.587341	3.757355	0.0176349
		100		0.050832	0.00044447	0.579787	4.74781	0.0087438
		200		0.025378	0.00011049	3.266505	-14.47678	0.0043536
		500		0.010142	1.7618 × 10 ⁻⁵	10.98053	-74.17124*	0.0017371
1.5	3.5	1.5	5	0.119954	0.006565	1.215589	5.318137	0.054729
			20	0.479814	0.105038	1.215591	5.318139	0.218914
			50	1.199535	0.656487	1.215591	5.318139	0.547285
			200	4.798140	10.50380	1.215591	5.318139	2.189139
			500	11.99535	65.64873	1.215591	5.318139	5.472848
			1000	23.99070	262.5949	1.215591	5.318139	10.94570

3.5. Some generating functions (GF)

The moment generating function (MGF) can be derived using (8) as

$$M_Z(t) = \sum_{s=0}^{\infty} \eta_s M_{s \bullet}(t; \beta),$$

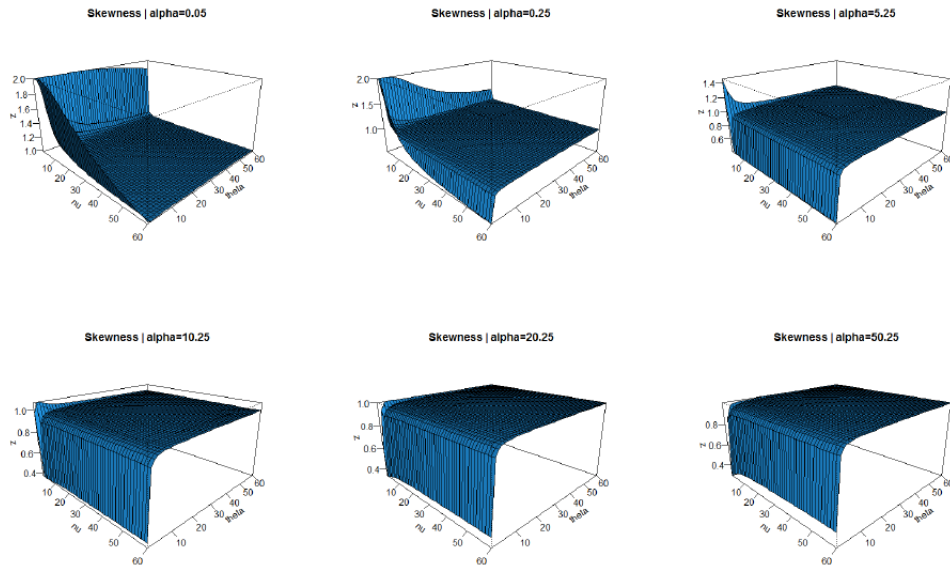


Figure 2. Three dimensional Skewness plots for parameter α .

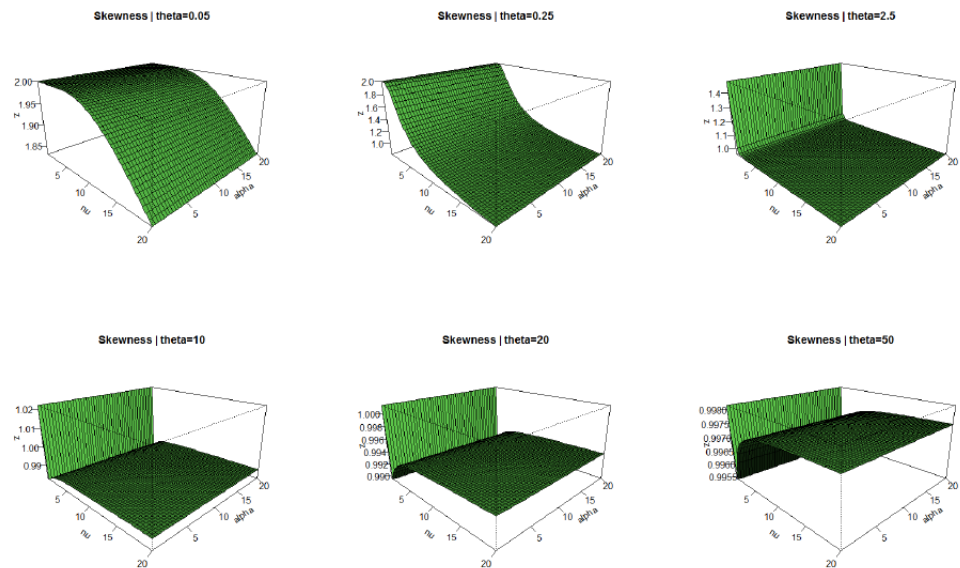


Figure 3. Three dimensional Skewness plots for parameter θ .

where $M_{s^\bullet}(t; \alpha, \beta)$ is the MGF of the ExpP model, then

$$M_Z(t) = \sum_{s=0}^{\infty} \sum_{r=0}^{\infty} \sum_{\kappa=0}^r \frac{t^r}{r!} \eta_s s^\bullet \beta^r (-1)^\kappa \binom{r}{\kappa} \mathcal{B}\left(s^\bullet, 1 + \frac{1}{\alpha}(\kappa - r)\right) |_{(\alpha > r)}$$

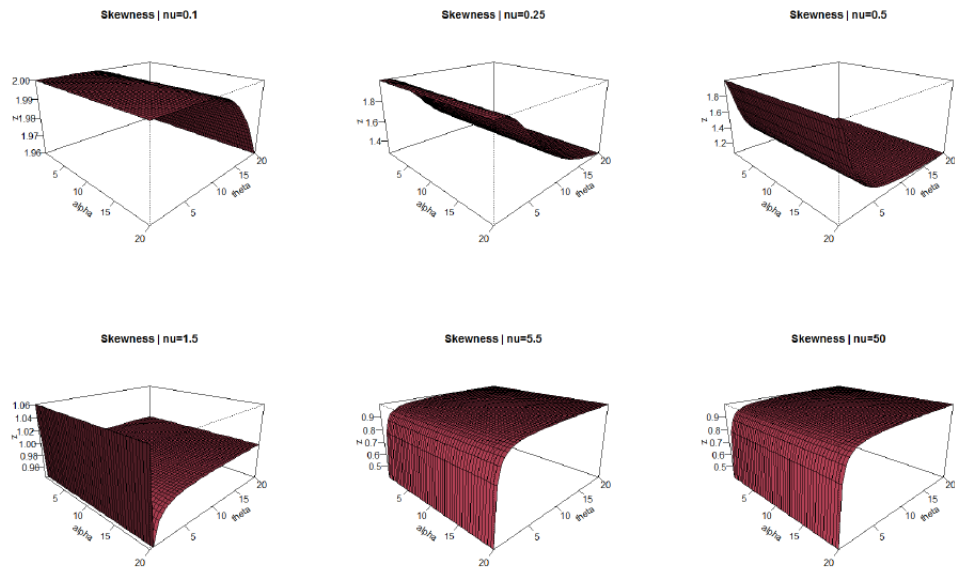


Figure 4. Three dimensional Skewness plots for parameter ν .

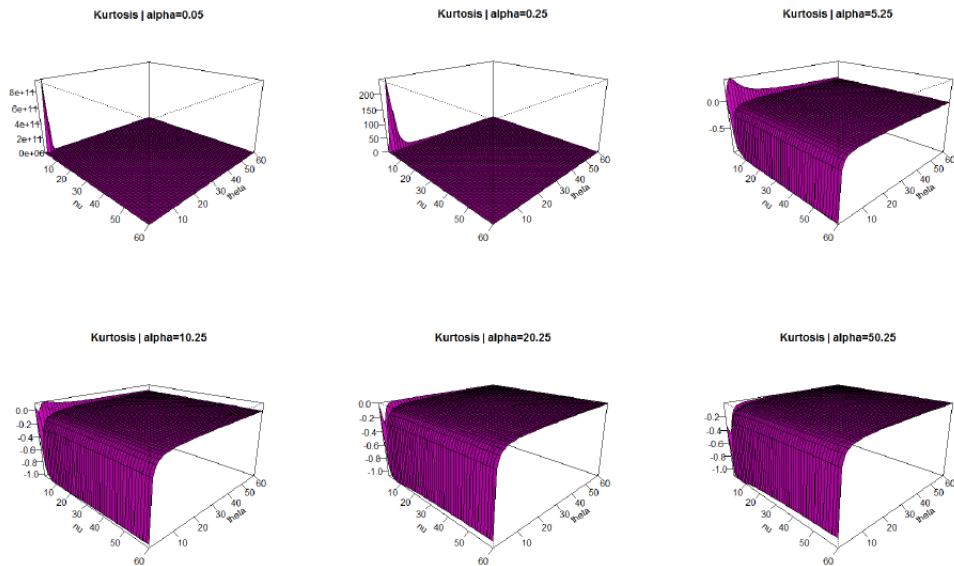


Figure 5. Three dimensional kurtosis plots for parameter α .

The first r derivatives of $M_Z(t)$, with respect to t at $t = 0$, yield the first r moments about the origin, i.e.,

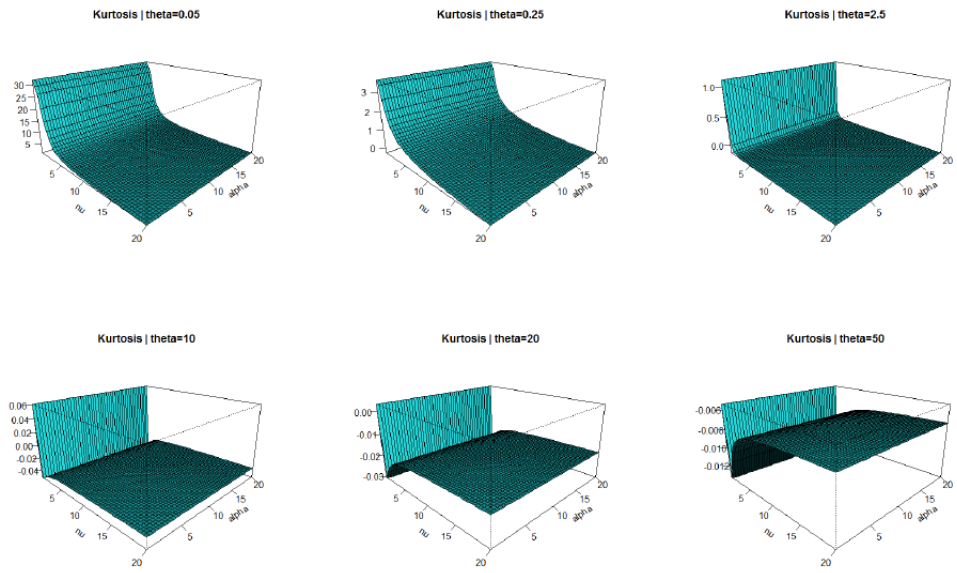


Figure 6. Three dimensional kurtosis plots for parameter θ .

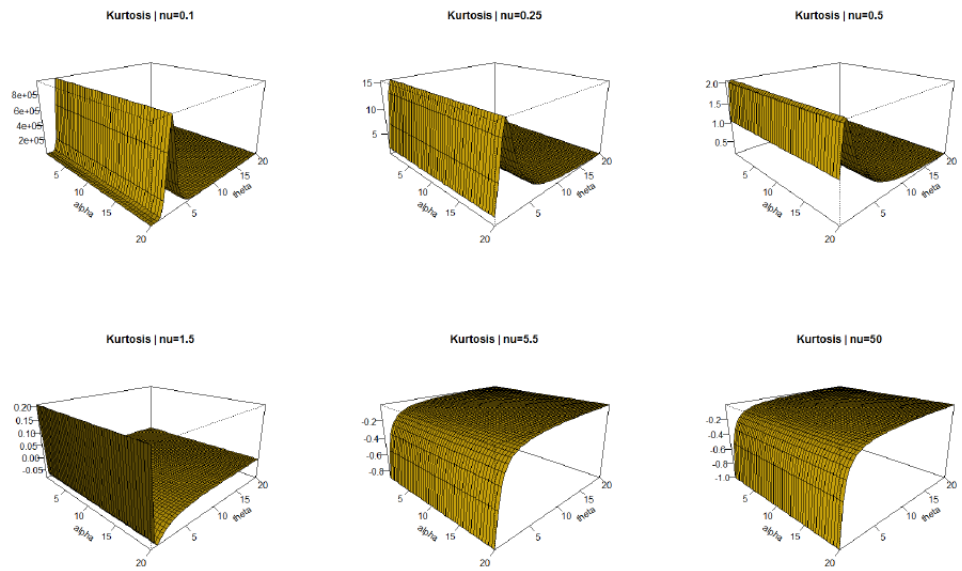


Figure 7. Three dimensional kurtosis plots for parameter ν .

$$\mu'_{r,z} = \mathbb{E}(z^r) = \frac{d^r}{dt^r} M_z(t) |_{(t=0 \text{ and } r=1,2,3,\dots)},$$

The generating function GF (CGF) is the logarithm of the MGF. Thus, r^{th} cumulant, say κ_r , can be obtained from

$$\kappa_{r,z} = \frac{d^r}{dt^r} \log \left[\sum_{s=0}^{\infty} \sum_{r=0}^{\infty} \sum_{\kappa=0}^r \frac{t^r}{r!} \eta_s s^\bullet \beta^r (-1)^\kappa \binom{r}{\kappa} \mathcal{B} \left(s^\bullet, 1 + \frac{1}{\alpha} (\kappa - r) \right) \right] \Big|_{(t=0, \text{ and } r=1,2,3,\dots)}.$$

The 1^{st} cumulant is the mean ($\kappa_{1,z} = \mu'_1$), the 2^{nd} cumulant is the variance, and the 3^{rd} cumulant is the same as the 3^{rd} central moment $\kappa_{3,z} = \mu_{3,z}$. But 4^{th} and higher-order cumulants are not equal to central moments, that being said $\kappa_{1,z} = \mu'_{1,z}, \kappa_{2,z} = \mu'_{2,z} - \mu'^2_{1,z} = \mu_{2,z}$ and $\kappa_{3,z} = \mu'_{3,z} - 3\mu'_{2,z}\mu'_{1,z} + 2\mu'^3_{1,z} = \mu_{3,z}$. In some cases theoretical treatments of problems in terms of cumulants are simpler than those using moments. In particular, when two or more RVs are statistically independent, the r^{th} order cumulant of their sum is equal to the sum of their r^{th} order cumulants. Moreover, the cumulants can be also obtained from $\kappa_{r,z}|_{r \geq 1} = \mu'_{r,z} - \sum_{m=0}^{r-1} \binom{r-1}{m-1} \mu'_{r-m,z} \kappa_{m,z}$.

3.6. Reversed residual life function

The n^{th} moment of the reversed residual life, say $V_{n,z}(t) = \mathbf{E} [(t - z)^n |_{z \leq t, t > 0 \text{ and } n=1,2,\dots}]$. Then, $V_{n,z}(t)$ can be written as

$$V_{n,z}(t) = \frac{1}{F_{v,\theta,\zeta}(t)} \int_0^t (t - z)^n dF_{v,\theta,\zeta}(z).$$

Then, the n^{th} moment of the reversed residual life of Z becomes

$$V_{n,z}(t) = \frac{1}{F_{v,\theta,\zeta}(t)} \sum_{s=0}^{\infty} \sum_{\kappa=0}^r \eta_s^* s^\bullet \beta^r (-1)^\kappa \binom{r}{\kappa} \mathcal{B}_t \left(s^\bullet, 1 + \frac{1}{\alpha} (\kappa - r) \right) |_{(\alpha > r)},$$

where

$$\eta_s^* = \eta_s \sum_{h=0}^n (-1)^h \binom{n}{h} t^{n-h}.$$

4. Estimation

In this Section, non-Bayesian and Bayesian estimation methods are considered. In first subsection, we will consider four non-Bayesian estimation methods such as the MLE, OLSE, WLSE and the KE methods. In the second subsection, the Bayesian estimation method under the squared error loss function (SELF).

4.1. Non-Bayesian estimation methods

4.1.1. *The MLE* Let z_1, z_2, \dots, z_n be a random sample from size n from the OBP distribution with parameters v, θ, α and β . Let $\underline{\xi}^\top$ be the 4×1 parameter vector. For determining the MLE of $\underline{\xi}$, we have the log-likelihood function

$$\begin{aligned} \ell(\underline{\xi}) &= (v-1) \sum_{i=1}^n \log [1 - \nabla_\beta (z_i)^{-\alpha}] + n \log \left(v\theta \frac{\alpha}{\beta} \right) - (\alpha v\theta + 1) \sum_{i=1}^n \nabla_\beta (z_i) \\ &\quad - (1 + \theta) \sum_{i=1}^n \log \left\{ [1 - \nabla_\beta (z_i)^{-\alpha}]^v + \nabla_\beta (z_i)^{-\alpha v\theta} \right\}. \end{aligned}$$

The components of the score vector, $\mathbf{U}(\underline{\xi}) = \frac{\partial \ell(\underline{\xi})}{\partial \underline{\xi}} = \left(\frac{\partial \ell(\underline{\xi})}{\partial v}, \frac{\partial \ell(\underline{\xi})}{\partial \theta}, \frac{\partial \ell(\underline{\xi})}{\partial \alpha}, \frac{\partial \ell(\underline{\xi})}{\partial \beta} \right)^\top$, are available if needed. Setting $\mathbf{U}(v) = \mathbf{U}(\theta) = \mathbf{U}(\alpha) = \mathbf{U}(\beta) = \mathbf{0}$ and solving them simultaneously yields the MLE $\hat{\underline{\xi}} = (\hat{v}, \hat{\theta}, \hat{\alpha}, \hat{\beta})^\top$. To solve these equations, it is usually more convenient to use nonlinear optimization methods such as the quasi-Newton algorithm to numerically maximize ℓ . For interval estimation of the parameters, we obtain the 4×4 observed information matrix $\mathbf{J}(\underline{\xi}) = \{\partial^2 \ell(\underline{\xi}) / \partial m \partial w\} \text{symbol} |_{(m,w=v,\theta,\alpha,\beta)}$.

4.1.2. *OLS* Let $F_{\underline{\xi}}(\mathbf{z}_{[i:n]})$ denotes the CDF of OBP model and let $\mathbf{z}_1 < \mathbf{z}_2 < \dots < \mathbf{z}_n$ be the n ordered RS. The OLSEs are obtained upon minimizing

$$\mathbf{OLSE}(\underline{\xi}) = \sum_{i=1}^n [F_{\underline{\xi}}(\mathbf{z}_{[i:n]}) - \tau_{(i,n)}]^2,$$

then, we have

$$\mathbf{OLSE}(\underline{\xi}) = \sum_{i=1}^n \left(1 - \frac{\nabla_{\beta}(\mathbf{z}_{[i:n]})^{-\alpha v \theta}}{\left\{ [1 - \nabla_{\beta}(\mathbf{z}_{[i:n]})^{-\alpha}]^v + \nabla_{\beta}(\mathbf{z}_{[i:n]})^{-\alpha v} \right\}^{\theta}} - \tau_{(i,n)} \right)^2,$$

where $\tau_{(i,n)} = \frac{i}{n+1}$. The LSEs are obtained via solving the following non-linear equations

$$0 = \sum_{i=1}^n \left(1 - \frac{\nabla_{\beta}(\mathbf{z}_{[i:n]})^{-\alpha v \theta}}{\left\{ [1 - \nabla_{\beta}(\mathbf{z}_{[i:n]})^{-\alpha}]^v + \nabla_{\beta}(\mathbf{z}_{[i:n]})^{-\alpha v} \right\}^{\theta}} - \tau_{(i,n)} \right) \varsigma_v(\mathbf{z}_{[i:n]}, \underline{\xi}),$$

$$0 = \sum_{i=1}^n \left(1 - \frac{\nabla_{\beta}(\mathbf{z}_{[i:n]})^{-\alpha v \theta}}{\left\{ [1 - \nabla_{\beta}(\mathbf{z}_{[i:n]})^{-\alpha}]^v + \nabla_{\beta}(\mathbf{z}_{[i:n]})^{-\alpha v} \right\}^{\theta}} - \tau_{(i,n)} \right) \varsigma_{\theta}(\mathbf{z}_{[i:n]}, \underline{\xi}),$$

$$0 = \sum_{i=1}^n \left(1 - \frac{\nabla_{\beta}(\mathbf{z}_{[i:n]})^{-\alpha v \theta}}{\left\{ [1 - \nabla_{\beta}(\mathbf{z}_{[i:n]})^{-\alpha}]^v + \nabla_{\beta}(\mathbf{z}_{[i:n]})^{-\alpha v} \right\}^{\theta}} - \tau_{(i,n)} \right) \varsigma_{\alpha}(\mathbf{z}_{[i:n]}, \underline{\xi}),$$

$$0 = \sum_{i=1}^n \left(1 - \frac{\nabla_{\beta}(\mathbf{z}_{[i:n]})^{-\alpha v \theta}}{\left\{ [1 - \nabla_{\beta}(\mathbf{z}_{[i:n]})^{-\alpha}]^v + \nabla_{\beta}(\mathbf{z}_{[i:n]})^{-\alpha v} \right\}^{\theta}} - \tau_{(i,n)} \right) \varsigma_{\beta}(\mathbf{z}_{[i:n]}, \underline{\xi}),$$

where $\varsigma_v(\mathbf{z}_{[i:n]}, \underline{\xi})$, $\varsigma_{\theta}(\mathbf{z}_{[i:n]}, \underline{\xi})$, $\varsigma_{\alpha}(\mathbf{z}_{[i:n]}, \underline{\xi})$ and $\varsigma_{\beta}(\mathbf{z}_{[i:n]}, \underline{\xi})$ defined above.

4.1.3. *WLSE* The WLSE are obtained by minimizing the function $\mathbf{WLSE}(\underline{\xi})$ WRT v, θ, α and β

$$\mathbf{WLSE}(\underline{\xi}) = \sum_{i=1}^n \omega_{(i,n)} [F_{\underline{\xi}}(\mathbf{z}_{[i:n]}) - \tau_{(i,n)}]^2,$$

where $\omega_{(i,n)} = [(1+n)^2(2+n)] / [i(1+n-i)]$. The WLSEs are obtained by solving

$$0 = \sum_{i=1}^n \omega_{(i,n)} \left(1 - \frac{\nabla_{\beta}(\mathbf{z}_{[i:n]})^{-\alpha v \theta}}{\left\{ [1 - \nabla_{\beta}(\mathbf{z}_{[i:n]})^{-\alpha}]^v + \nabla_{\beta}(\mathbf{z}_{[i:n]})^{-\alpha v} \right\}^{\theta}} - \tau_{(i,n)} \right) \varsigma_v(\mathbf{z}_{[i:n]}, \underline{\xi}),$$

$$0 = \sum_{i=1}^n \omega_{(i,n)} \left(1 - \frac{\nabla_{\beta}(\mathbf{z}_{[i:n]})^{-\alpha v \theta}}{\left\{ [1 - \nabla_{\beta}(\mathbf{z}_{[i:n]})^{-\alpha}]^v + \nabla_{\beta}(\mathbf{z}_{[i:n]})^{-\alpha v} \right\}^{\theta}} - \tau_{(i,n)} \right) \varsigma_{\theta}(\mathbf{z}_{[i:n]}, \underline{\xi}),$$

$$0 = \sum_{i=1}^n \omega_{(i,n)} \left(1 - \frac{\nabla_{\beta} (\mathbf{z}_{[i:n]})^{-\alpha v \theta}}{\left\{ \left[1 - \nabla_{\beta} (\mathbf{z}_{[i:n]})^{-\alpha} \right]^v + \nabla_{\beta} (\mathbf{z}_{[i:n]})^{-\alpha v} \right\}^{\theta}} - \tau_{(i,n)} \right) \varsigma_{\alpha} (\mathbf{z}_{[i:n]}, \underline{\xi}),$$

and

$$0 = \sum_{i=1}^n \omega_{(i,n)} \left(1 - \frac{\nabla_{\beta} (\mathbf{z}_{[i:n]})^{-\alpha v \theta}}{\left\{ \left[1 - \nabla_{\beta} (\mathbf{z}_{[i:n]})^{-\alpha} \right]^v + \nabla_{\beta} (\mathbf{z}_{[i:n]})^{-\alpha v} \right\}^{\theta}} - \tau_{(i,n)} \right) \varsigma_{\beta} (\mathbf{z}_{[i:n]}, \underline{\xi})$$

where $\varsigma_v(\mathbf{z}_{[i:n]}, \underline{\xi})$, $\varsigma_{\theta}(\mathbf{z}_{[i:n]}, \underline{\xi})$, $\varsigma_{\alpha}(\mathbf{z}_{[i:n]}, \underline{\xi})$ and $\varsigma_{\beta}(\mathbf{z}_{[i:n]}, \underline{\xi})$ defined above.

4.1.4. *KE method* The Kolmogorov estimates (KEs) $\hat{v}, \hat{\theta}, \hat{\alpha}$ and $\hat{\beta}$ of v, θ, α and β are obtained by minimizing the function

$$KE = KE(v, \theta, \alpha, \beta) = \max_{1 \leq i \leq n} \left\{ \frac{i}{n} - F_{\underline{\xi}}(\mathbf{z}_{[i:n]}), F_{\underline{\xi}}(\mathbf{z}_{[i:n]}) - \frac{i-1}{n} \right\}$$

4.2. *Bayesian estimation*

Assume the gamma priors of the parameters v, θ, α and β of the following forms

$$\pi_{1;(\zeta_1, \xi_1)}(v) \sim \text{Gamma}(\zeta_1, \xi_1), \pi_{2;(\zeta_2, \xi_2)}(\theta) \sim \text{Gamma}(\zeta_2, \xi_2)$$

$$\pi_{3;(\zeta_3, \xi_3)}(\alpha) \sim \text{Gamma}(\zeta_3, \xi_3) \text{ and } \pi_{4;(\zeta_4, \xi_4)}(\beta) \sim \text{Uniform}(\zeta_4, \xi_4),$$

Assume that the parameters are independently distributed. The joint prior distribution can be written as

$$\begin{aligned} \pi_{(\zeta_i, \xi_i)}(v, \theta, \alpha, \beta) &= \frac{\xi_1^{\zeta_1} \xi_2^{\zeta_2} \xi_3^{\zeta_3} \xi_4^{\zeta_4}}{\Gamma(\zeta_1)\Gamma(\zeta_2)\Gamma(\zeta_3)\Gamma(\zeta_4)} v^{\zeta_1-1} \theta^{\zeta_2-1} \alpha^{\zeta_3-1} \beta^{\zeta_4-1} \\ &\times \exp[-(v\xi_1 + \theta\xi_2 + \alpha\xi_3 + \beta\xi_4)] \end{aligned}$$

The posterior distribution $\pi(v, \theta, \alpha, \beta | \underline{Z})$ of the parameters is defined as

$$\pi(v, \theta, \alpha, \beta | \underline{Z}) \propto \text{likelihood}(\underline{\xi} | \underline{Z}) \times \pi_{(\zeta_i, \xi_i)}(v, \theta, \alpha, \beta).$$

Under squared error loss function, the Bayesian estimators of v, θ, α and β are the means of their marginal posteriors and defined as

$$\begin{aligned} \hat{v}_{\text{Bayesian}} &= \int_{v, \theta, \alpha, \beta} v \pi(v, \theta, \alpha, \beta | \underline{Z}) \, d\beta d\alpha d\theta dv, \hat{\theta}_{\text{Bayesian}} = \int_{\theta, \alpha, v, \beta} \theta \pi(v, \theta, \alpha, \beta | \underline{Z}) \, d\beta dv d\alpha d\theta, \\ \hat{\alpha}_{\text{Bayesian}} &= \int_{\alpha, \theta, v, \beta} \alpha \pi(v, \theta, \alpha, \beta | \underline{Z}) \, d\beta dv d\theta d\alpha \text{ and } \hat{\beta}_{\text{Bayesian}} = \int_{\beta, v, \theta, \alpha} \beta \pi(v, \theta, \alpha, \beta | \underline{Z}) \, d\alpha d\theta dv d\beta, \end{aligned}$$

respectively. It is not possible to obtain the Bayesian estimates through the above formulae. So, the numerical approximation are needed. We propose the use of MCMC techniques namely Gibbs sampler and Metropolis Hastings (M-H) algorithm. Since the conditional posteriors of the parameters v, θ, α and β cannot be obtained in any standard forms, therefore, using a hybrid MCMC for drawing samples from the joint posterior of the parameters is suggested. the full conditional posteriors of v, θ, α and β can be easily derived. The simulation algorithm is given by

1. Provide the initial values, say v, θ, α and β then at $i^{(\text{th})}$ stage,
2. Using M-H algorithm, we generate $v_{(i)} \sim \pi_1(v_{(i)} | \theta_{(i), \alpha_{(i)}, \beta_{(i)}, \underline{Z})}$;
3. Using M-H algorithm, we generate $\theta_{(i)} \sim \pi_2(\theta_{(i)} | v_{(i), \alpha_{(i)}, \beta_{(i)}, \underline{Z})}$;

4. Using M-H algorithm, we generate $\alpha_{(i)} \sim \pi_2 (\alpha | v_{(i)}, \theta_{(i)}, \beta_{(i)}, \underline{Z})$;
5. Using M-H algorithm, we generate $\beta_{(i)} \sim \pi_3 (\beta | v_{(i)}, \theta_{(i)}, \alpha_{(i)}, \underline{Z})$;
6. Repeat steps 2 – 5, $M = 100000$ times to get the samples of size M from the corresponding posteriors of interest. Obtain the Bayesian estimates of v, θ, α and β using the following formulae

$$\hat{v}_{(\text{Bayesian})} = \frac{1}{M - M_0} \sum_{h=M_0+1}^M v^{[h]}, \hat{\theta}_{(\text{Bayesian})} = \frac{1}{M - M_0} \sum_{h=M_0+1}^M \theta^{[h]}$$

$$\hat{\alpha}_{(\text{Bayesian})} = \frac{1}{M - M_0} \sum_{h=M_0+1}^M \alpha^{[h]} \text{ and } \hat{\beta}_{(\text{Bayesian})} = \frac{1}{M - M_0} \sum_{h=M_0+1}^M \beta^{[h]},$$

respectively, where $M_0 (\approx 50000)$ is the burn-in period of the generated MCMC.

5. Simulation studies for comparing estimation methods

A numerical simulation is performed in to compare the classical estimation methods. The simulation study is based on $N=1000$ generated data sets from the OBP version where $n = 50, 100, 150$ and 300 and

	α	β	θ	v
I	0.6	0.5	0.8	2.0
II	1.2	0.9	0.4	0.9
III	1.5	1.5	1.5	1.5

The estimates are compared in terms of their

- 1-Bias $\text{BIAS}(\underline{\xi})$;
- 2-Root mean-standard error $\text{RMSE}(\underline{\xi})$;
- 3-the mean of the absolute difference between the theoretical and the estimates “D-abs” and
- 4-the maximum absolute difference between the true parameters and estimates “D-max”. Where

$$\text{BIAS}(v) = \frac{1}{B} \sum_{i=1}^B (\hat{v}_i - v), \quad \text{BIAS}(\theta) = \frac{1}{B} \sum_{i=1}^B (\hat{\theta}_i - \theta),$$

$$\text{BIAS}(\alpha) = \frac{1}{B} \sum_{i=1}^B (\hat{\alpha}_i - \alpha) \text{ and } \text{BIAS}(\beta) = \frac{1}{B} \sum_{i=1}^B (\hat{\beta}_i - \beta)$$

$$\text{RMSE}(v) = \sqrt{\frac{1}{B} \sum_{i=1}^B (\hat{v}_i - v)^2}, \quad \text{RMSE}(\theta) = \sqrt{\frac{1}{B} \sum_{i=1}^B (\hat{\theta}_i - \theta)^2},$$

$$\text{RMSE}(\alpha) = \sqrt{\frac{1}{B} \sum_{i=1}^B (\hat{\alpha}_i - \alpha)^2} \text{ and } \text{RMSE}(\beta) = \sqrt{\frac{1}{B} \sum_{i=1}^B (\hat{\beta}_i - \beta)^2}$$

$$\text{D-abs} = \frac{1}{nB} \sum_{i=1}^B \sum_{j=1}^n |F_{\hat{v}, \hat{\theta}, \hat{\alpha}, \hat{\beta}}(w_{ij}) - F_{\hat{v}, \hat{\theta}, \hat{\alpha}, \hat{\beta}}(t_{ij})|$$

and

$$\text{D-max} = \frac{1}{B} \sum_{i=1}^B \max_j |F_{\hat{v}, \hat{\theta}, \hat{\alpha}, \hat{\beta}}(w_{ij}) - F_{\hat{v}, \hat{\theta}, \hat{\alpha}, \hat{\beta}}(t_{ij})|.$$

From Tables 2, 3 and 4 we note that:

- 1-The $BIAS(\xi)$ tend to zero when n increases which means that all estimators are non-biased.
- 2-The $RMSE(\xi)$ tend to zero when n increases which means incidence of consistency property.

Table 2: Simulation results for blend I.

n		BIAS				RMSE				D	
		α	β	θ	ν	α	β	θ	ν	D-abs	D-max
50	MLE	0.00080	0.01097	0.00975	0.02018	0.05360	0.08511	0.11800	0.25189	0.00287	0.00512
	OLS	0.00023	0.01038	0.00560	-0.08725	0.05526	0.08647	0.13487	0.30543	0.00728	0.01358
	WLS	0.00500	0.02796	0.00893	0.01640	0.11195	0.15991	0.30269	0.10696	0.00863	0.01475
	KE	0.01374	-0.00721	0.04123	-0.01073	0.05907	0.08539	0.14970	0.38113	0.02621	0.03798
	Bayes	0.00398	0.01568	0.03254	0.33775	0.05745	0.08026	0.10377	0.36938	0.02256	0.03717
100	MLE	0.00129	0.00535	0.00798	0.02097	0.03744	0.05787	0.08208	0.17399	0.00248	0.00475
	OLS	0.00065	0.00460	0.00441	-0.03183	0.03869	0.05907	0.09347	0.21176	0.00211	0.00379
	WLS	0.00712	0.01080	0.01685	0.01777	0.07897	0.11146	0.21620	0.07382	0.00448	0.00781
	KE	0.00707	-0.00421	0.02055	0.02126	0.04024	0.06001	0.09900	0.28228	0.01430	0.02181
	Bayes	0.00729	0.04256	0.07521	0.14118	0.03976	0.07488	0.09686	0.19151	0.01959	0.03429
150	MLE	0.00156	0.00211	0.00596	0.01141	0.02993	0.04646	0.06472	0.13968	0.00235	0.00441
	OLS	0.00141	0.00146	0.00508	-0.02001	0.03124	0.04715	0.07501	0.016616	0.00154	0.00307
	WLS	0.00536	0.00568	0.01342	0.01155	0.06129	0.08744	0.16899	0.05827	0.00273	0.00426
	KE	0.00582	-0.00486	0.01658	0.00590	0.03221	0.04760	0.07936	0.21698	0.01210	0.01784
	Bayes	-0.00358	-0.00315	-0.05250	-0.05662	0.03878	0.04345	0.08228	0.19074	0.01916	0.03325
300	MLE	0.00017	0.00194	0.00185	0.00588	0.02114	0.03265	0.04585	0.10084	0.00065	0.00106
	OLS	-0.00021	0.00198	0.00027	-0.01669	0.02224	0.03364	0.05306	0.12376	0.00170	0.00319
	WLS	0.00088	0.00659	0.00156	0.00813	0.04187	0.06288	0.11659	0.04153	0.00321	0.00563
	KE	0.00219	-0.00113	0.00646	-0.00210	0.02282	0.03408	0.05580	0.15528	0.00417	0.00603
	Bayes	0.03087	-0.03077	0.04631	0.16941	0.03068	0.04330	0.06821	0.12107	0.00580	0.00917

Table 3: Simulation results for blend II.

n		BIAS				RMSE				D	
		α	β	θ	ν	α	β	θ	ν	D-abs	D-max
50	MLE	0.02788	0.05455	0.00880	0.01173	0.18563	0.35095	0.06044	0.11516	0.00683	0.01350
	OLS	0.02315	0.05498	0.00709	0.00706	0.21622	0.36186	0.06881	0.16892	0.00442	0.00913
	WLS	0.01899	0.05403	0.00596	0.02253	0.19359	0.36204	0.06252	0.13636	0.00653	0.01262
	KE	0.07836	-0.01383	0.02427	0.02780	0.24575	0.33801	0.07720	0.18985	0.03616	0.05639
	Bayes	-0.19824	0.00974	0.01411	0.04312	0.24994	0.21532	0.06691	0.11820	0.05550	0.03858
100	MLE	0.01000	0.03649	0.00307	0.00650	0.12325	0.24593	0.04019	0.08044	0.00226	0.00404
	OLS	0.00176	0.04617	0.00038	-0.00230	0.14635	0.25991	0.04682	0.11518	0.00534	0.00828
	WLS	0.00513	0.05259	0.00143	0.01957	0.13272	0.26865	0.04309	0.09157	0.00387	0.00691
	KE	0.02951	0.01036	0.00910	0.01022	0.16007	0.25481	0.05060	0.13287	0.01190	0.01917
	Bayes	-0.05279	-0.16918	0.05055	0.08384	0.19302	0.21199	0.05662	0.10322	0.03506	0.08749
150	MLE	0.00263	0.02757	0.00074	0.00202	0.09923	0.19196	0.03234	0.06614	0.00206	0.00372
	OLS	0.00679	0.02059	0.00206	0.00268	0.11844	0.19843	0.03791	0.09320	0.00128	0.00249
	WLS	0.00848	0.02724	0.00260	0.01843	0.10600	0.21046	0.03447	0.07537	0.00441	0.00830
	KE	0.02476	-0.00370	0.00769	0.01246	0.12804	0.20073	0.04054	0.10438	0.01223	0.01942
	Bayes	-0.17180	-0.01111	0.00525	-0.01755	0.16913	0.20290	0.05171	0.06349	0.03470	0.05529
300	MLE	0.00510	0.01484	0.00153	0.00399	0.07060	0.13355	0.02300	0.04620	0.00133	0.00260
	OLS	0.00103	0.01383	0.00027	-0.00042	0.08214	0.13814	0.02635	0.06489	0.00138	0.00222
	WLS	0.00370	0.01881	0.00109	0.01164	0.07459	0.14737	0.02428	0.05348	0.00233	0.00417
	KE	0.00918	0.00284	0.00284	0.00324	0.08606	0.13878	0.02734	0.06999	0.00379	0.00610
	Bayes	-0.09043	-0.19675	0.04463	-0.00204	0.11547	0.09998	0.03676	0.04062	0.02906	0.05239

Table 4: Simulation results for blend III.

n	BIAS				RMSE				D		
	α	β	θ	ν	α	β	θ	ν	D-abs	D-max	
50	MLE	0.00998	0.01608	0.02478	0.02660	0.15515	0.20023	0.22342	0.17201	0.00356	0.00692
	OLS	0.00977	0.01309	0.02195	-0.02893	0.16803	0.20343	0.25625	0.24265	0.00524	0.00886
	WLS	0.00878	0.01192	0.01731	0.03202	0.15788	0.20076	0.22766	0.20061	0.00374	0.00647
	KE	0.05577	-0.03849	0.09372	-0.02485	0.18571	0.20171	0.29133	0.28028	0.03834	0.05543
	Bayes	0.29424	-0.36041	0.14774	-0.03986	0.30536	0.38261	0.22526	0.17783	0.17937	0.25659
100	MLE	0.00390	0.01037	0.01150	0.01402	0.11173	0.14382	0.15891	0.12593	0.00170	0.00264
	OLS	0.01089	-0.00168	0.01969	-0.01795	0.11359	0.13804	0.17148	0.16423	0.00746	0.01083
	WLS	0.00983	-0.00038	0.01639	0.03038	0.10863	0.13984	0.15400	0.13601	0.00457	0.00916
	KE	0.02399	-0.01490	0.04074	-0.01276	0.12439	0.14499	0.19049	0.20399	0.01651	0.02378
	Bayes	0.05525	-0.15882	0.07136	-0.12017	0.13964	0.17427	0.13996	0.13171	0.06436	0.09694
150	MLE	0.00633	0.00049	0.01217	0.00479	0.08774	0.11118	0.12507	0.10424	0.00319	0.00519
	OLS	-0.00200	0.01173	-0.00024	0.00260	0.09947	0.12169	0.14955	0.14502	0.00311	0.00456
	WLS	0.00009	0.01013	0.00255	0.03159	0.09527	0.12312	0.13427	0.11760	0.00432	0.00810
	KE	0.01201	-0.00571	0.02084	-0.00562	0.09777	0.11529	0.14826	0.16543	0.00796	0.01147
	Bayes	-0.03666	0.11917	-0.06103	-0.00945	0.08742	0.15873	0.12070	0.08974	0.04253	0.06291
300	MLE	0.00212	0.00192	0.00446	0.00532	0.06218	0.08054	0.08712	0.07095	0.00081	0.00162
	OLS	0.00253	0.00103	0.00495	-0.00464	0.06707	0.08203	0.10040	0.10000	0.00153	0.00226
	WLS	0.00436	-0.00045	0.00722	0.02002	0.06465	0.08327	0.09059	0.08067	0.00245	0.00469
	KE	0.00768	-0.00487	0.01296	-0.00103	0.06878	0.08250	0.10397	0.11651	0.00514	0.00751
	Bayes	0.02506	-0.04209	0.05482	0.02469	0.06617	0.08058	0.10813	0.08053	0.02287	0.03505

6. Applications for comparing classical methods

6.1. Comparing classical methods under failure times

The first real data set (data set I) represents the data on failure times of 84 aircraft windshield given in Murthy et al. [58]. The data are: 0.0400, 1.866, 2.3850, 3.443, 0.3010, 1.876, 2.4810, 3.467, 0.309, 1.8990, 2.610, 3.4780, 0.557, 1.9110, 2.625, 3.5780, 0.943, 1.9120, 2.632, 3.5950, 1.0700, 1.914, 2.6460, 3.699, 1.1240, 1.981, 2.661, 3.7790, 1.248, 2.0100, 2.688, 3.9240, 1.2810, 2.038, 2.820, 3, 4.035, 1.281, 2.0850, 2.890, 4.121, 1.3030, 2.089, 2.902, 4.167, 1.4320, 2.097, 2.934, 4.2400, 1.480, 2.135, 2.962, 4.2550, 1.505, 2.154, 2.9640, 4.278, 1.506, 2.190, 3.000, 4.3050, 1.568, 2.1940, 3.103, 4.376, 1.615, 2.2230, 3.114, 4.449, 1.6190, 2.224, 3.1170, 4.485, 1.652, 2.2290, 3.166, 4.570, 1.652, 2.3000, 3.344, 4.602, 1.7570, 2.324, 3.3760, 4.663. We consider the Cramér-Von Mises (W^*) and the Anderson-Darling (A^*) statistics. Figure 6 gives probability-probability (P-P) plots for comparing all methods under the failure times data set. From Table 5, the MLE method is the best method with $W^*=0.05840$ and $A^*=0.56749$ then Bayesian method with $W^*=0.06309$ and $A^*=0.63239$.

Table 5: The values of estimators A^* and W^* under failure times.

Method	$\hat{\nu}$	$\hat{\theta}$	$\hat{\alpha}$	$\hat{\beta}$	A^*	W^*
MLE	2.23386	32.84160	17.54380	262.208	0.56749	0.05840
OLS	3.30660	1.24718	0.94249	2.45219	1.24500	0.14386
WLS	3.77635	1.92859	0.90976	2.63173	0.82385	0.08386
KE	2.65987	1.56671	1.28125	3.97197	1.08694	0.12031
Bayes	2.03701	43.35538	5.03022	97.70641	0.63239	0.06309

6.2. Comparing classical methods under service times

The second real data set (data set II) represents the data on service times of 63 aircraft windshield given in Murthy et al. [58]. The data are: 0.046, 1.436, 2.592, 0.140, 1.492, 2.600, 0.150, 1.580, 2.670, 0.248, 1.7190, 2.717, 0.2800, 1.794, 2.819, 0.3130, 1.915, 2.820, 0.389, 1.9200, 2.878, 0.487, 1.9630, 2.950, 0.622, 1.978, 3.0030, 0.9000, 2.053, 3.1020, 0.952, 2.065, 3.3040, 0.9960, 2.117, 3.483, 1.0030, 2.137, 3.500, 1.0100, 2.141, 3.6220, 1.085, 2.163,

3.6650, 1.092, 2.183, 3.695, 1.1520, 2.2400, 4.015, 1.183, 2.3410, 4.628, 1.2440, 2.435, 4.806, 1.249, 2.4640, 4.881, 1.262, 2.5430, 5.140. Many other useful real life data sets can be found in Aryal et al. [18] and Ibrahim and Yousof [36]. Figure 7 gives P-P plots for comparing all methods under the failure times data set. From Table 6, the MLE method is the best method with $W^{\star}=0.09443$ and $A^{\star}=0.57283$ then the OLS method with $W^{\star}=0.09443$ and $A^{\star}=0.71474$.

Table 6: The values of estimators A^{\star} and W^{\star} under service times data.

Method	\hat{v}	$\hat{\theta}$	$\hat{\alpha}$	$\hat{\beta}$	A^{\star}	W^{\star}
MLE	1.57877	17.0739	77.31319	1150.47	0.57283	0.09443
OLS	1.176663	5.15567	1.59013	9.75342	0.71474	0.11726
WLS	1.89100	5.97335	0.92384	5.14160	0.78311	0.12841
ME	2.16031	1.38096	1.07536	2.52004	1.45874	0.23917
Bayes	1.33126	304.370	0.93765	155.711	0.84289	0.13915

7. Graphical assessment for the MLEs

Graphically and using the biases and mean squared errors (MSEs), we can perform the simulation experiments to assess the finite sample behavior of the MLEs. The assessment was based on $n=1000$ replication for all $n|_{(n=50,100,\dots,500)}$. The following algorithm is considered:

1. Generate $n=1000$ samples of size $n|_{(n=50,100,\dots,500)}$ from the OBP distribution using (7);
2. Compute the MLEs for the $n=1000$ samples, say

$$[\hat{v}_n, \hat{\theta}_n, \hat{\alpha}_n, \hat{\beta}_n] |_{(n=1,2,\dots,1000)},$$

3. Compute the SEs of the MLEs for the 1000 samples, say

$$[S_{\hat{v}_n}, S_{\hat{\theta}_n}, S_{\hat{\alpha}_n}, S_{\hat{\beta}_n}] |_{(n=1,2,\dots,1000)}.$$

The standard errors (SEs) were computed by inverting the observed information matrix.

4. Compute the biases and mean squared errors given for $\xi = v, \theta, \alpha, \beta$. We repeated these steps for $n|_{(n=50,100,\dots,500)}$ with $v = \theta = \alpha = \beta = 1$, so computing biases ($\text{Bias}_{\xi}(n)$), mean squared errors (MSEs) ($\text{MSE}_{\xi}(n)$) for $\xi = v, \theta, \alpha, \beta$ and $n|_{(n=50,100,\dots,500)}$ where

$$\text{Bias}_{\xi}(n)|_{(\xi=v,\theta,\alpha,\beta)} = \frac{1}{1000} \sum_{n=1}^{1000} (\hat{\xi}_n - \xi),$$

and

$$\text{MSE}_{\xi}(n)|_{(\xi=v,\theta,\alpha,\beta)} = \frac{1}{1000} \sum_{n=1}^{1000} (\hat{\xi}_n - \xi)^2.$$

Figures 8, 9, 10 and 11 gives the biases (left panels) and MSEs (right panels) for the parameters v, θ, α and β respectively.

The left panels from show how the four biases vary with respect to n . The right panels show how the four MSEs vary with respect to n . The broken line in red in Figure 8 corresponds to the biases being 0. From Figures 8, 9, 10 and 11 (left panels), the biases for each parameter are generally negative and tends to zero as $n \rightarrow \infty$. From Figures 8, 9, 10 and 11 (right panels), the MSEs for each parameter decrease to zero as $n \rightarrow \infty$.

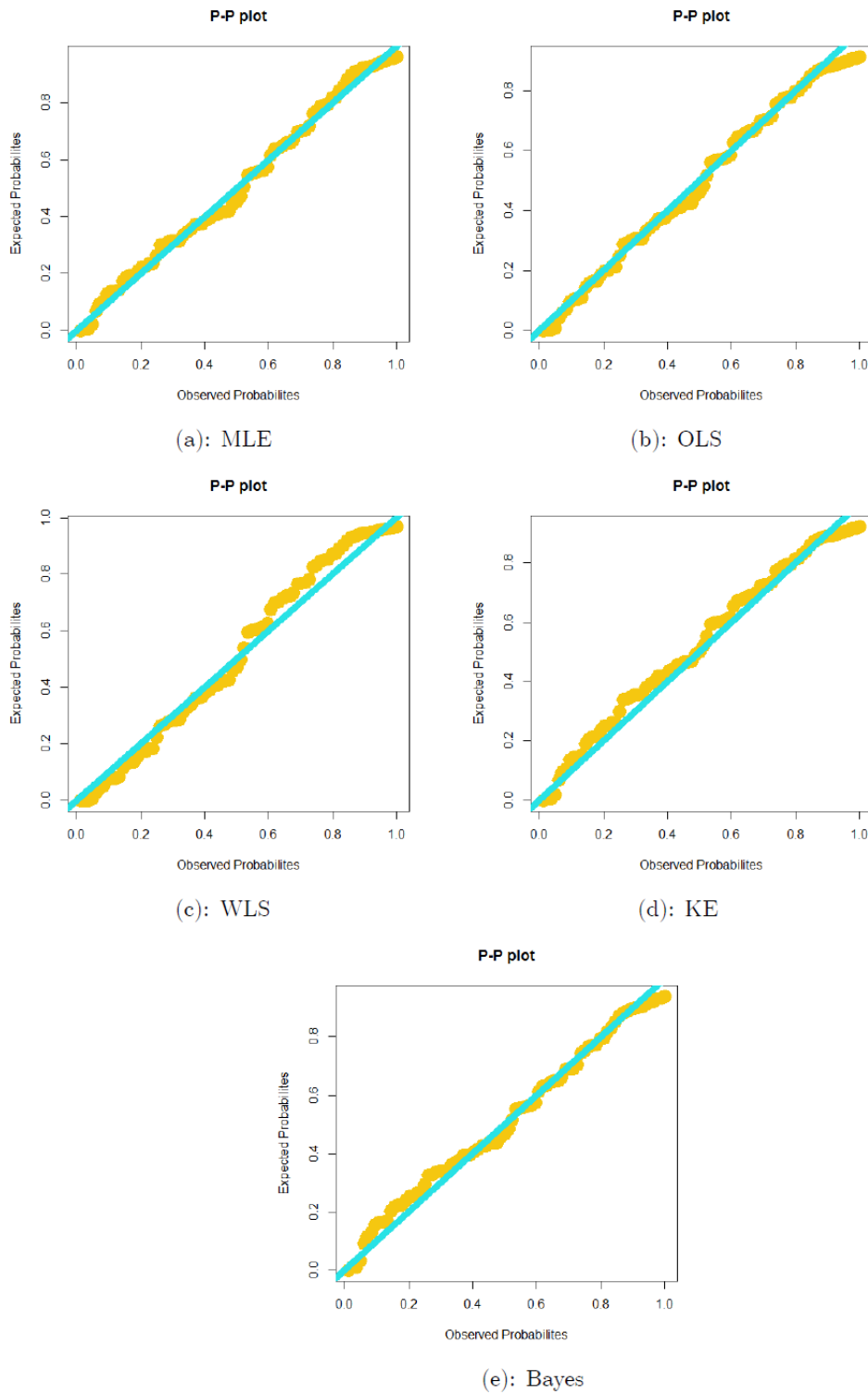


Figure 8. P-P plots for comparing classical methods under failure times.

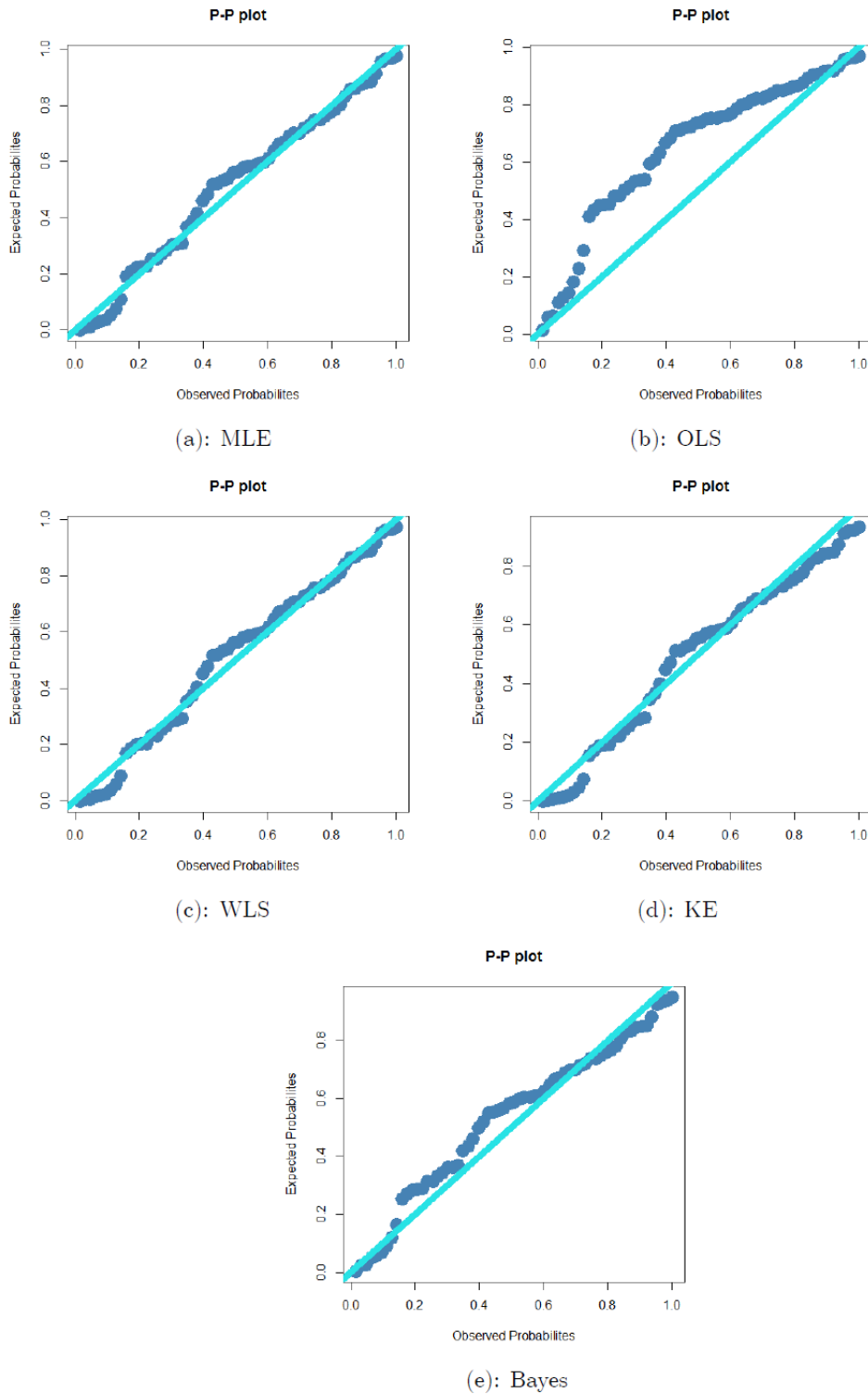
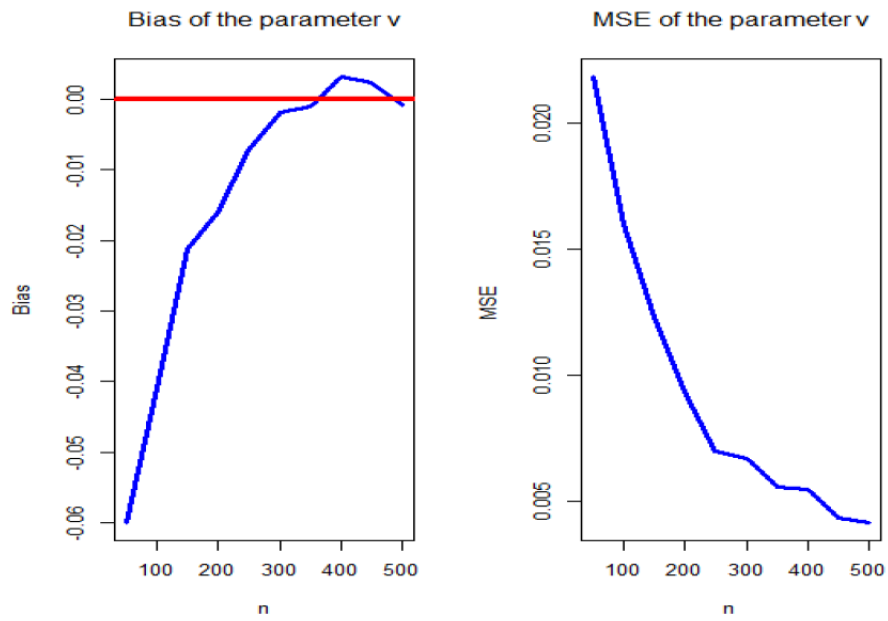
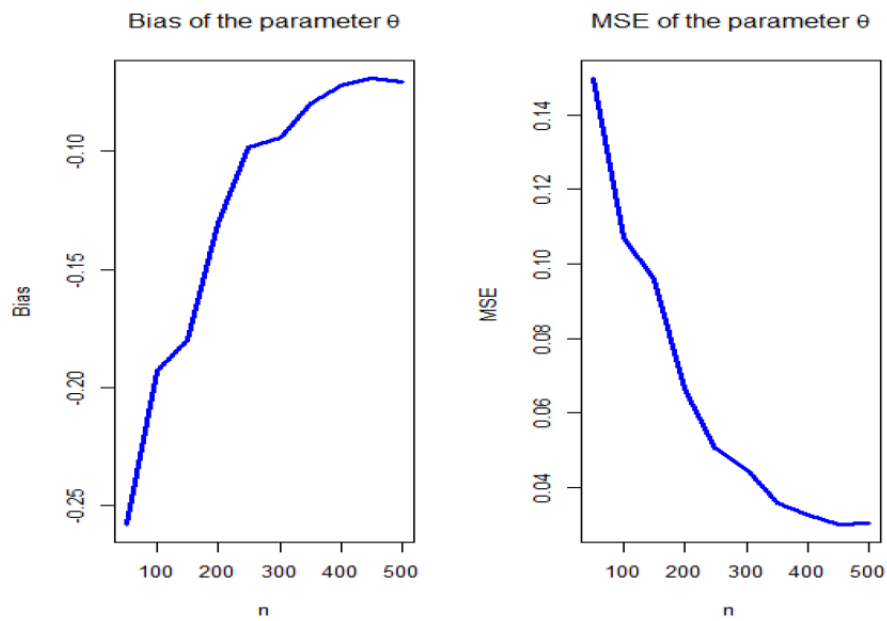


Figure 9. P-P plots for comparing classical methods under service times data

Figure 10. biases and mean squared errors for the parameter v .Figure 11. biases and mean squared errors for the parameter θ .

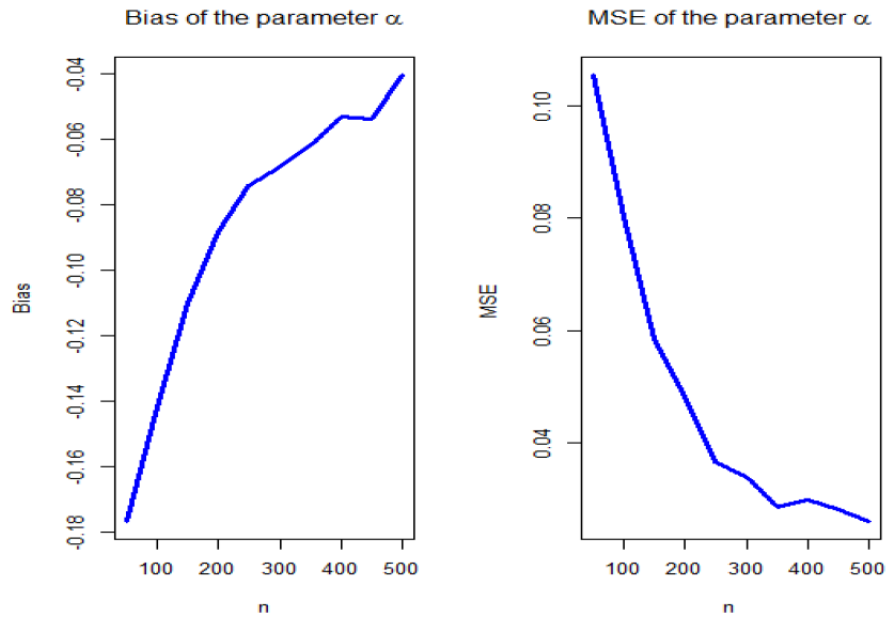


Figure 12. biases and mean squared errors for the parameter α .

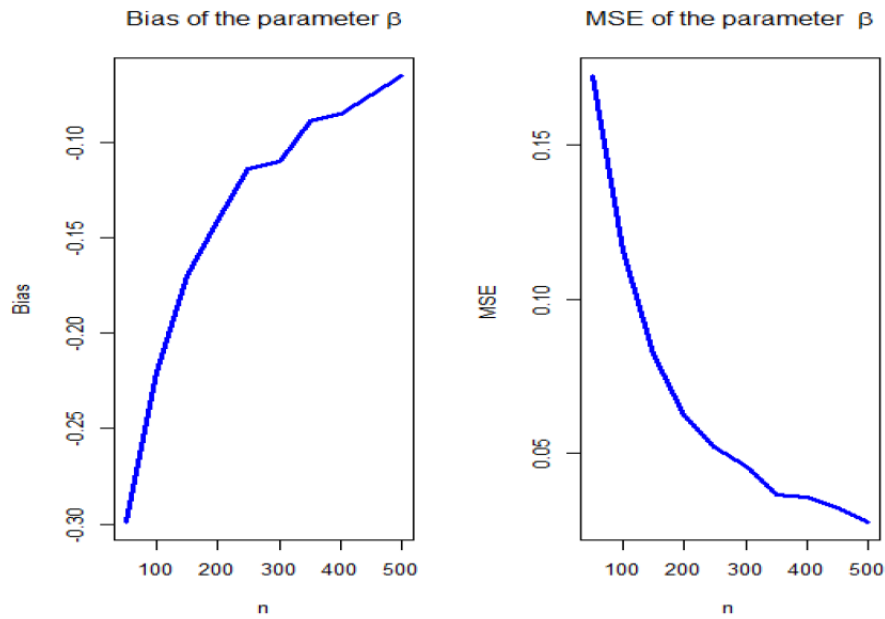


Figure 13. biases and mean squared errors for the parameter β .

8. Applications

In this section, we provide two real life applications to two real data sets to illustrate the importance and flexibility of the OBP model. We compare the fit of the OBP with some well-known competitive models (see Table 7)

Table 7: Competitive models.

N.	Model	Abbreviation	Author
1	Pareto type II	P	Lomax [41]
2	Exponentiated P	ExpP	Gupta et al. [30]
3	Kumaraswamy P	KumP	Lemonte and Cordeiro [40]
4	Macdonald P	McP	Lemonte and Cordeiro [40]
5	Beta P	BP	Lemonte and Cordeiro [40]
6	Gamma P	GamP	Cordeiro et al. [23]
7	Transmuted Topp-Leone P	TTLP	Yousof et al. [68]
8	Reduced TTLP	RTTLP	Yousof et al. [68]
9	Odd log-logistic P	OLLP	Altun et al. [12]
10	Reduced OLLP	ROLLP	Altun et al. [12]
11	Reduced Burr-Hatke P	RBHP	Yousof et al. [73]
12	Reduced OBP	ROBP	New
13	Proportional reversed hazard rate P	PRHRP	New
14	Special generalized mixture P	SGMP	Chesneau and Yousof [22]

For checking the normality, the Quantile-Quantile (Q-Q) plot is sketched. For exploring the HRF for real data, the total time test (TTT) plot is provided. For exploring the initial shape of real data nonparametrically, kernel density estimation (KDE) is provided. Figures 12 and 13 give the box plot, normal Q-Q plot, TTT plot and nonparametric KDE for data set **I** and data set **II** respectively. Based on Figures 12(a) and 13(a), we note that no extreme values were found in the two real life data sets. Based on Figures 12(b) and 13(b), we note that the normality is nearly exists. Based on Figures 12(c) and 13(c), we note that the HRF is “increasing” for the two real life data sets. Figures 12(d) and 13(d) show nonparametric KDE for exploring the data.

We estimate the unknown parameters of each model by maximum likelihood using “L-BFGS-B” method and the goodness-of-fit statistics Akaike information criterion (AIC), Bayesian IC (BIC), Consistent AIC (CAIC), Hannan-Quinn IC (HQIC), Anderson-Darling (A^*) and Cramér–von Mises (W^*) are used to compare the five models. In general, the smaller the values of these statistics, the better the fit to the data. The required computations are obtained by using the “maxLik” and “gofest” sub-routines in R-software. For failure times data: the analysis results of are listed in Tables 8 and 9. Table 8 gives the MLEs and standard errors (SEs) for failure times data. Table 9 gives the $-\hat{\ell}$ and goodness-of-fits statistics for failure times data. For service times data: the analysis results of are listed in Tables 10 and 11. Table 10 gives the MLEs and SEs for service times data. Table 11 give the $-\hat{\ell}$ and goodness-of-fits statistics for the service times data. Based on Tables 9 and 11, we note that the OBP model gives the lowest values for the AIC, CAIC, BIC, HQIC, A^* and W^* among all fitted models. Hence, it could be chosen as the best model under these criteria.

Figure 14 gives the estimated PDF (EPDF) plot, estimated CDF (ECDF) plot, probability-probability (P-P) plot and estimated HRF (EHRF) plot for data set **I**. Figure 15 gives the EPDF plot, ECDF plot, P-P plot and EHRF plot for data set **II**. From Figures 14 and 15, it is noted that the OBP provides a very adequate fits to the empirical functions.

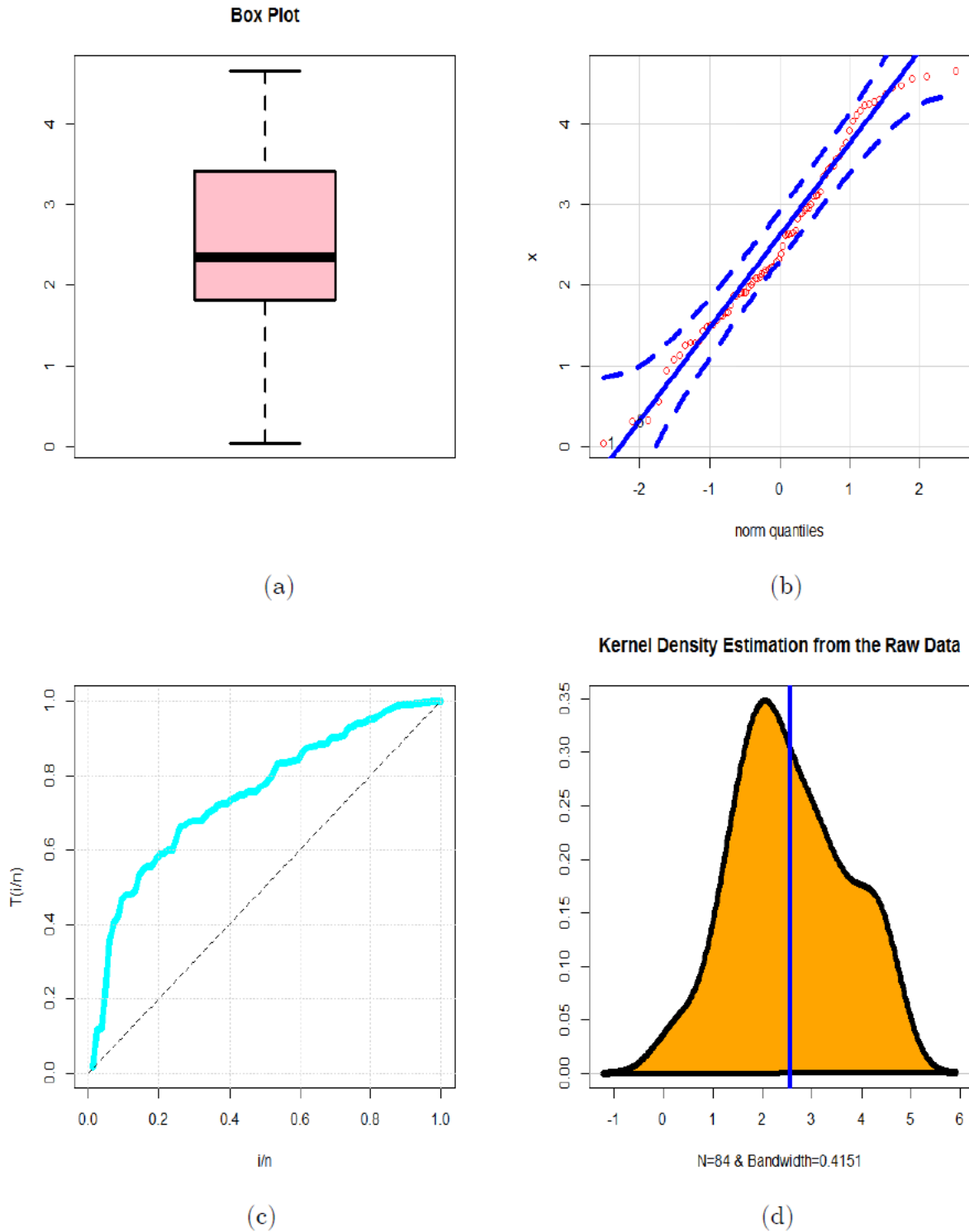


Figure 14. Box plot, normal Q-Q plot, TTT plot and nonparametric KDE for data set I.

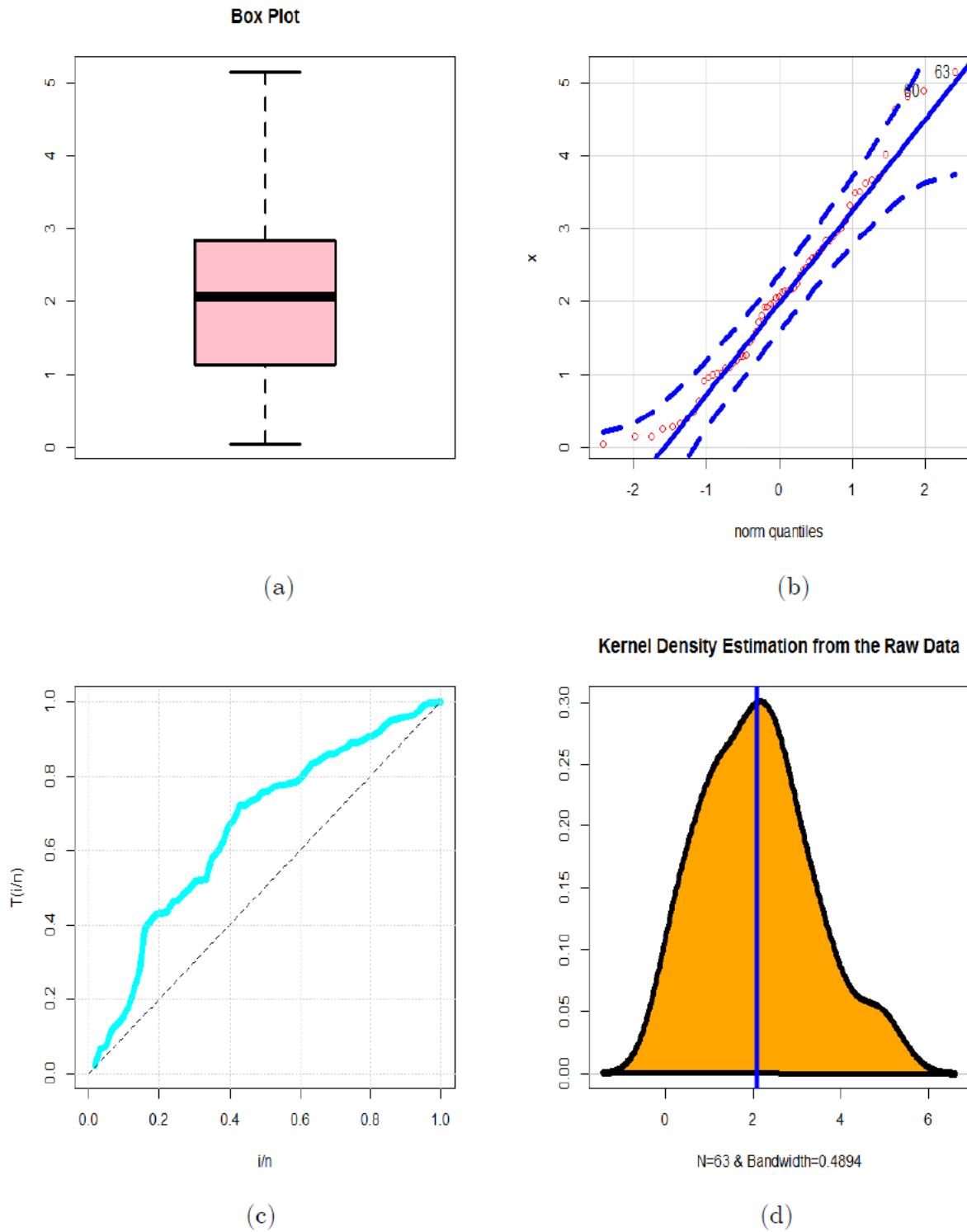


Figure 15. Box plot, normal Q-Q plot, TTT plot and nonparametric KDE for data set II.

Table 8: MLEs and SEs for failure times data.

Model	Estimates				
OBP (v, θ, α, β)	2.27526 (7.2387)	57.35316 (21.9898)	6.576097 (9.18131)	119.4169 (277.895)	
McP($v, \theta, c, \alpha, \beta$)	2.1875 (0.5211)	119.1751 (140.297)	12.4171 (20.845)	19.9243 (38.9601)	75.6606 (147.24)
TTLP(v, θ, α, β)	-0.80750 (0.13960)	2.47663 (0.54176)	(15608.2) (1602.37)	(38628.3) (123.936)	
KumP(v, θ, α, β)	2.6150 (0.3822)	100.2756 (120.486)	5.27710 (9.8116)	78.6774 (186.005)	
BP(v, θ, α, β)	3.60360 (0.6187)	33.63870 (63.7145)	4.830700 (9.23820)	118.8374 (428.927)	
PRHRP(θ, α, β)	3.73×10^6 1.01×10^6	4.707×10^{-1} (0.00001)	4.49×10^6 37.14684		
RTTLP(v, θ, α)	-0.84732 (0.10010)	5.52057 (1.18479)	1.15678 (0.09588)		
SGMP(v, α, β)	-1.04×10^{-1} (0.1223)	9.83×10^6 (4843.3)	1.18×10^7 (501.04)		
ROBP(v, θ, α)	3.54793 (0.3141)	30.63743 (55.8404)	0.24295 (0.1026)		
OLLP(v, α, β)	2.32636 (2.14×10^{-1})	(7.17×10^5) (1.19×10^4)	2.34×10^6 (2.61×10^1)		
GamP(v, α, β)	3.58760 (0.5133)	52001.49 (7955.00)	37029.66 (81.1644)		
ExpP(v, α, β)	3.62610 (0.6236)	20074.51 (2041.83)	26257.68 (99.7417)		
ROLLP(v, α)	3.890564 (0.36524)	0.57316 (0.01946)			
RBHP(α, β)	10801754 (983309)	51367189 (232312)			
P(α, β)	51425.35 (5933.49)	131789.8 (296.119)			

Table 9: $-\hat{\ell}$ and goodness-of-fits statistics for failure times data.

Model	$\hat{\ell}$	AIC	CAIC	BIC	HQIC	A^*	W^*
OBP	-129.5287	267.057	267.562	276.779	270.964	0.5675	0.0584
McP	-129.8023	269.6045	270.3640	281.8178	274.5170	0.6672	0.0858
KumP	-132.4048	272.8096	273.3096	282.5802	276.7396	0.6645	0.0658
ROBP	-134.3584	274.7169	275.0169	282.0093	277.6484	0.9439	0.1004
OLLP	-134.4235	274.8470	275.1470	282.1394	277.7785	0.9407	0.1009
TTLP	-135.5700	279.1400	279.6464	288.8633	283.0487	1.1257	0.1270
GamP	-138.4042	282.8083	283.1046	290.1363	285.7559	1.3666	0.1618
BP	-138.7177	285.4354	285.9354	295.2060	289.3654	1.4084	0.1680
ExpP	-141.3997	288.7994	289.0957	296.1273	291.7469	1.7435	0.2194
ROLLP	-142.8452	289.6904	289.8385	294.5520	291.6447	1.9566	0.2554
SGMP	-143.0874	292.1747	292.4747	299.4672	295.1062	1.3467	0.1578
RTTLP	-153.9809	313.9618	314.2618	321.2542	316.8933	3.7527	0.5592
PRHRP	-162.8770	331.7540	332.0540	339.0464	334.6855	1.3672	0.1609
P	-164.9884	333.9767	334.1230	338.8620	335.9417	1.3976	0.1665
RBHP	-168.6040	341.2081	341.3562	346.0697	343.1624	1.6711	0.2069

Table 10: MLEs and SEs for service times data.

Model	Estimates			
OBP(v, θ, α, β)	1.62783	318.092	2.21029	177.4062
	(0.16217)	(76.8271)	(4.5955)	(522.549)
KumP(v, θ, α, β)	1.6691	60.5673	2.56490	65.06400
	(0.2570)	(86.0131)	(4.7589)	(177.592)
BP(v, θ, α, β)	1.9218	31.2594	4.9684	169.5719
	(0.3184)	(316.841)	(50.528)	(339.207)
TTLP(v, θ, α, β)	(-0.6070)	1.785780	2123.391	4822.789
	(0.21371)	(0.41522)	(163.915)	(200.009)
PRHRP(θ, α, β)	1.59×10^6	3.93×10^{-1}	1.30×10^6	
	2.01×10^3	0.0004×10^{-1}	0.95×10^6	
RTTLP(v, θ, α)	-0.67145	2.74496	1.01238	
	(0.18746)	(0.6696)	(0.11405)	
SGMP(v, α, β)	-1.04×10^{-1}	6.45×10^6	6.33×10^6	
	(4.1×10^{-10})	(3.21×10^6)	(3.8573)	
ROBP(v, θ, α)	2.35836	23.13999	0.20245	
	(0.2413)	(41.18194)	(0.1325)	
OLLP(v, α, β)	1.66419	6.340×10^5	2.01×10^6	
	(1.79×10^{-1})	(1.68×10^4)	7.22×10^6	
GamP(v, α, β)	1.9073	35842.433	39197.57	
	(0.3213)	(6945.074)	(151.653)	
ExpP(v, α, β)	1.9145	22971.154	32881.99	
	(0.3482)	(3209.533)	(162.230)	
ROLLP(v, α)	2.37233	0.69109		
	(0.26825)	(0.04488)		
RBHP(α, β)	14055522	53203423		
	(422.005)	(28.52323)		
P(α, β)	99269.78	207019.37		
	(11863.5)	(301.2366)		

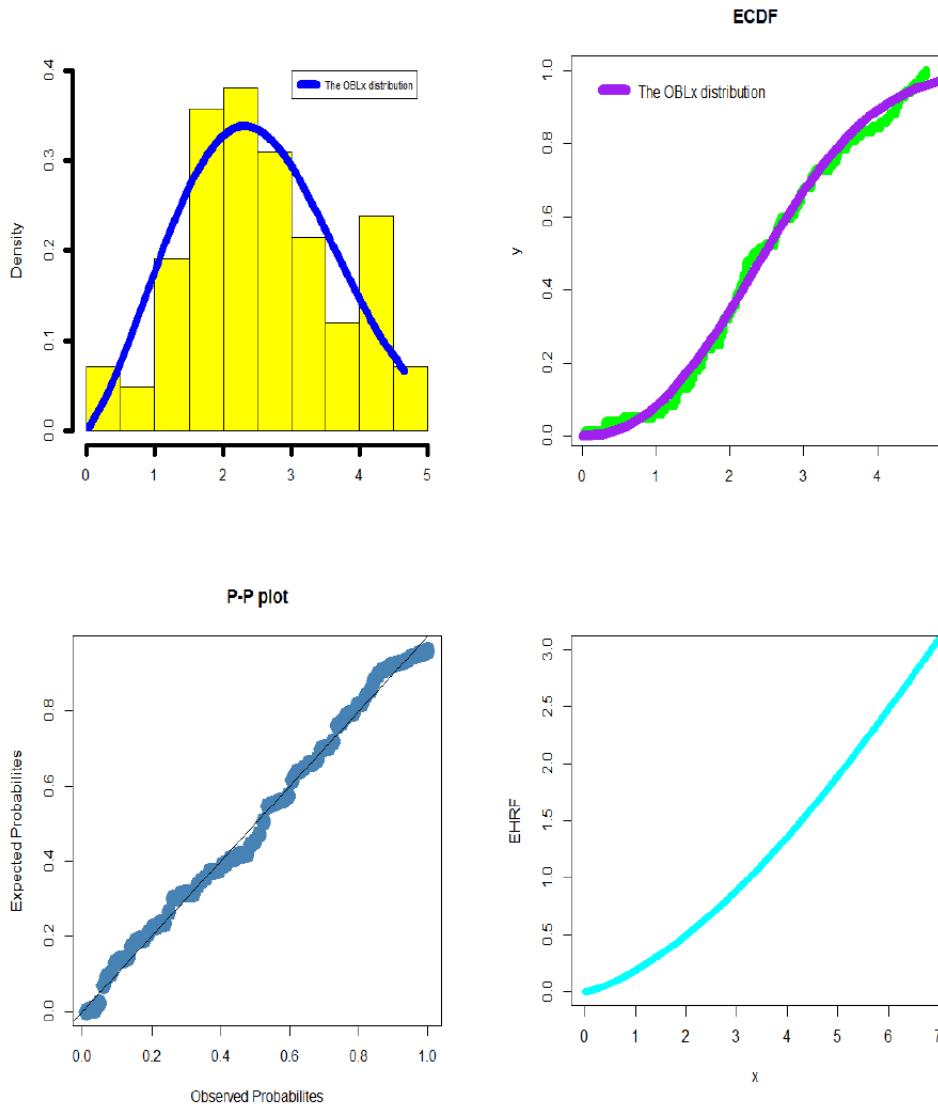


Figure 16. EPDF, ECDF, P-P plot and EHRF for data set I.

Table 11: $-\hat{\ell}$ and goodness-of-fits statistics for the service times data.

Model	$\hat{\ell}$	AIC	CAIC	BIC	HQIC	A^*	W^*
OBP	-100.0183	208.037	208.726	216.609	211.408	0.5728	0.0944
KumP	-100.8676	209.7353	210.4249	218.3078	213.1069	0.7391	0.1219
TTLP	-102.4498	212.8996	213.5893	221.4722	216.2713	0.9431	0.1554
GamP	-102.8332	211.6663	212.0730	218.0958	214.1951	1.1120	0.1836
SGMP	-102.8940	211.7881	212.1949	218.2175	214.3168	1.1134	0.1839
BP	-102.9611	213.9223	214.6119	222.4948	217.2939	1.1336	0.1872
ExpP	-103.5498	213.0995	213.5063	219.5289	215.6282	1.2331	0.2037
ROBP	-104.4258	214.8517	215.2584	221.2811	217.3804	1.2825	0.2115
OLLP	-104.9041	215.8082	216.2150	222.2376	218.3369	0.9424	0.1545
PRHRP	-109.2986	224.5973	225.004	231.0267	227.126	1.1264	0.1861
P	-109.2988	222.5976	222.7976	226.8839	224.2834	1.1265	0.1861
ROLLP	-110.7287	225.4573	225.6573	229.7436	227.1431	2.3472	0.3908
RTTLP	-112.1855	230.3710	230.7778	236.8004	232.8997	2.6875	0.4532
RBHP	-112.6005	229.2011	229.4011	233.4873	230.8869	1.3984	0.2316

9. Conclusions

A new lifetime model called the odd Burr Pareto type II (OBP) model is introduced and studied. The major motivation for the practicality of the OBP model is based on the wider importance of the standard Pareto type II model. The OBP density can be “right skewed” with heavy tail shape. The OBP failure rate can be “J-shape”, “decreasing” and “upside down (or increasing-constant-decreasing)”. The new OBP density can be expressed as a mixture of the exponentiated Pareto type II model. The skewness of the OBP distribution can range in the interval $(-69216.87, 98983.16)$. The spread for the kurtosis of the OBP model is ranging from 74.17124 to ∞ . The index of dispersion for the OBP model can be in $(0, 1)$ and also > 1 so it may be used as an “under-dispersed” and “over-dispersed” model. Bayesian and non-Bayesian estimation methods are considered. We assessed the performance of all methods via simulation study. Bayesian and many non-Bayesian estimation methods (such as such as the maximum likelihood estimation method, ordinary least square estimation method, weighted least square estimation method and the Kolmogorov estimation method) are compared in modeling real data via two applications. In modeling real data, the maximum likelihood method is the best estimation method. So, we used it in comparing competitive models. Before using the the maximum likelihood method, we performed simulation experiments to assess the finite sample behavior of it using the biases and mean squared errors. The OBP model could be chosen as the best model among Pareto type II, exponentiated Pareto type II, Kumaraswamy Pareto type II, Macdonald Pareto type II, beta Pareto type II, gamma Pareto type II, odd log-logistic Pareto type II, reduced odd log-logistic Pareto type II, reduced Burr-Hatke Pareto type II, reduced OBP and special generalized mixture Pareto type II distribution in modeling the “failure times” and the “service times” data sets.

As a future potential work we may consider the modified Nikulin-Rao-Robson goodness-of-fit test for distributional validation as presented by Abouelmagd et al. [1], Abouelmagd et al. [2], Ibrahim et al. [39], Ibrahim et al. [37], Goual et al. [28] and Goual et al. [29]. We may consider the modified Bagdonavičius-Nikulin Goodness-of-fit test for censored validation as presented by Mansour et al. ([53], [54], [56], [57], [52] and [55]), Yousof et al. [67] and Salah et al. [61]. Finally, we may characterize the OBP model using some characterizations theorems such as conditional expectation, truncated moment, hazard rate function, Mills ratio, certain functions of the random variable, first order statistic and conditional expectation of the record values as presented by Hamedani et al. ([46],[47] and [48]), Khalil et al. [49], Altun et al. ([13], [14], [15] and [17]), Alizadeh et al. ([7], [8] and [9]), Yousof et al. ([69], [70], [71], [72]), Altun et al. ([11] and [16]) and Ibrahim et al. [38].

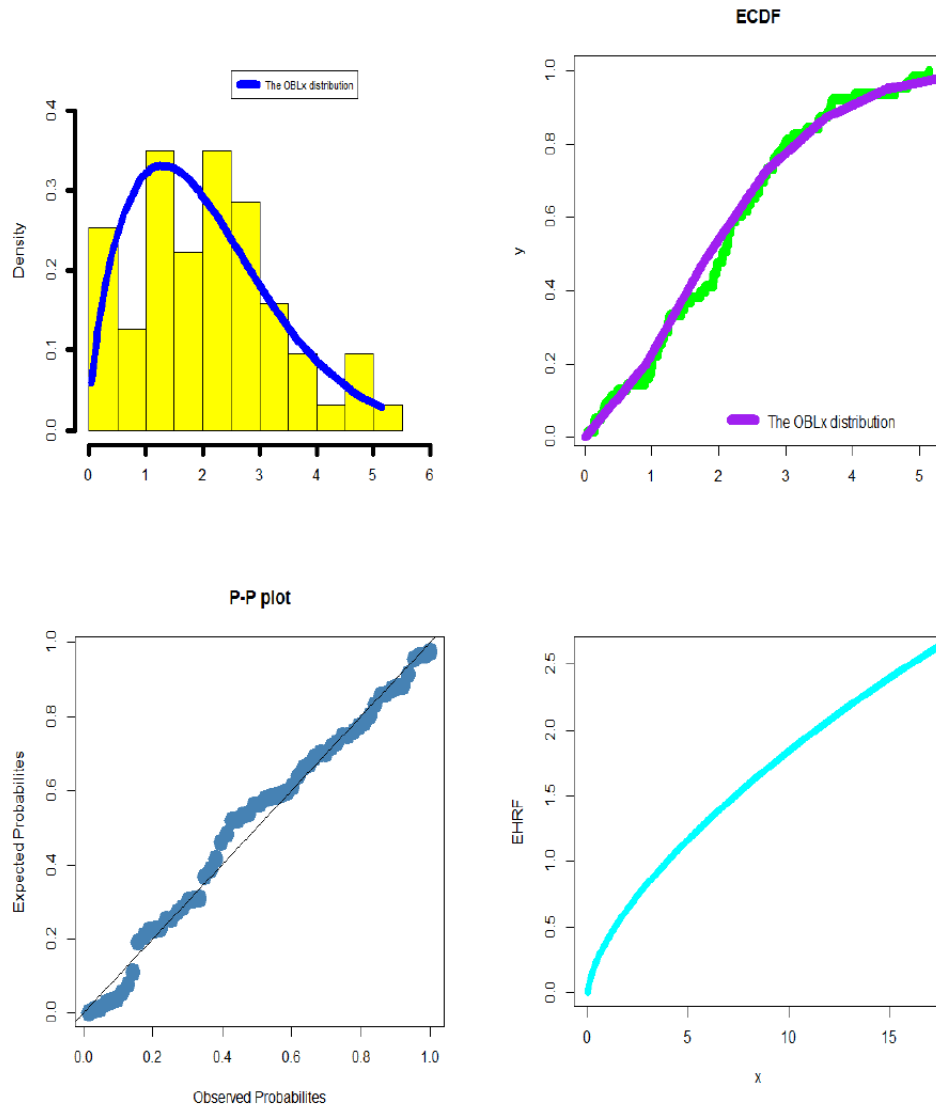


Figure 17. EPDF, ECDF, P-P plot and EHRF for data set II.

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